ETHzürich



Exercise Session 10 – Graphs & Paths Data Structures and Algorithms These slides are based on those of the lecture, but were adapted and

extended by the teaching assistant Adel Gavranović

Today's Schedule

Intro Follow-up Feedback for **code** expert Learning Objectives Minor Recap Theory Recap Shortest Paths All Pairs Shortest Paths Minimum Spanning Trees Code-Expert Exercise TSP Old Exam Ouestion Outro



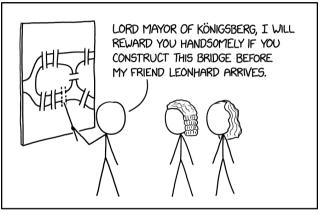
n.ethz.ch/~agavranovic

Exercise Session Material

▶ Adel's Webpage

▶ Mail to Adel

Comic of the Week



I TRIED TO USE A TIME MACHINE TO CHEAT ON MY ALGORITHMS FINAL BY PREVENTING GRAPH THEORY FROM BEING INVENTED.

1. Intro

Intro

- My throat is still a little sore
- New date for the session next week
 - Thu next week is a holiday
 - Alternatives should be listed on the course page soon
 - My session:
 - Wed 8th May
 - ▶ 16 18
 - CHN G 42

2. Follow-up

Follow-up from last exercise session

Quiz: Runtimes of Simple Operations (s. 13)

There are differences between undirected and directed graph's runtimes¹ especially for the "find all neighbours" operation

Quiz #3 (s. 17)

Was arguably a little too complicated for a tiny quiz question

Dijkstra Turning Exponential (s. 46)

Basically, every possible bit patters is a new possible combination that the algorithm has to check, i.e. exponentially many paths, thus $\mathcal{O}(2^n)$

¹think about it, but don't worry too much about it

3. Feedback for code expert

code expert

Master Solution for "Trees"

- Is on my homepage now
- If you notice errors, let me know

Non-deterministic Grading for "Amazing Mazes I"

- Don't be alarmed if you get a different grading for the same code
- (yes, just submit the better graded one)
- Long story short: the mazes are generated pseudo-randomly and that might cause some test to take longer than intended, yielding a virtual timer error
- Even the Master Solution suffered from this

Questions regarding **code** expert from your side?

4. Learning Objectives

Learning Objectives

Understand how and why...

- □ ...the A* algorithm
- \Box ...the Bellman-Ford algorithm
- \Box ...the Floyd-Warshall algorithm
- 🗆 ...the Jarnik-Prim-Dijkstra algorithm
- □ ...Kruskal's algorithm

works and when to use it

5. Minor Recap

Minor Recap

Quick recap on all of these

- Heuristic
- Transitive Closure
- Bellman-Ford Algorithm
- Floyd-Warshall Algorithm

6. Theory Recap

6.1 Shortest Paths

A*-Algorithm(G, s, t, \hat{h})

Input: Positively weighted Graph G = (V, E, c), starting point $s \in V$, end point $t \in V$, estimate $\hat{h}(v) \le \delta(v, t)$

Output: Existence and value of a shortest path from s to t

return failure

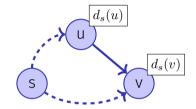
Properties

- The A*-Algorithm is an extension of the Dijkstra algorithm by a distance heuristic \hat{h} .
- A* is Dijkstra if $\hat{h} \equiv 0$
- underestimation: $\forall v \in V$: $\hat{h}(v) \leq \delta(v, t)$ If \hat{h} underestimates the real distance, the algorithm works correctly.
- Monotonicity: $\forall (u, u') \in E : \hat{h}(u') \leq \hat{h}(u) + c(u', u)$ If \hat{h} is monotone in addition, then the algorithm works efficiently.

General Weighted Graphs

 $\begin{aligned} & \operatorname{Relax}(u,v) \left(u,v \in V, \, (u,v) \in E \right) \\ & \text{if } d_s(v) > d_s(u) + c(u,v) \text{ then} \\ & \quad \left| \begin{array}{c} d_s(v) \leftarrow d_s(u) + c(u,v) \\ & \text{return true} \end{array} \right| \end{aligned}$

return false



Problem: cycles with negative weights can shorten the path, a shortest path is not guaranteed to exist.

Dynamic Programming Approach (Bellman)

Induction over number of edges $d_s[i, v]$: Shortest path from s to v via maximally i edges.

$$d_s[i, v] = \min\{d_s[i-1, v], \min_{(u,v)\in E}(d_s[i-1, u] + c(u, v)) \\ d_s[0, s] = 0, d_s[0, v] = \infty \ \forall v \neq s.$$

Algorithm Bellman-Ford(G, s)

Input: Graph G = (V, E, c), starting point $s \in V$ **Output:** If return value true, minimal weights d for all shortest paths from s, otherwise no shortest path.

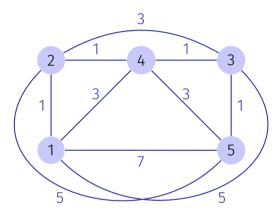
```
foreach u \in V do
 d_s[u] \leftarrow \infty; \pi_s[u] \leftarrow \mathsf{null}
d_{s}[s] \leftarrow 0:
for i \leftarrow 1 to |V| do
     f \leftarrow \mathsf{false}
     foreach (u, v) \in E do
      f \leftarrow f \lor \operatorname{Relax}(u, v)
     if f = false then return true
return false;
```

6.2 All Pairs Shortest Paths

DP Algorithm Floyd-Warshall(G)

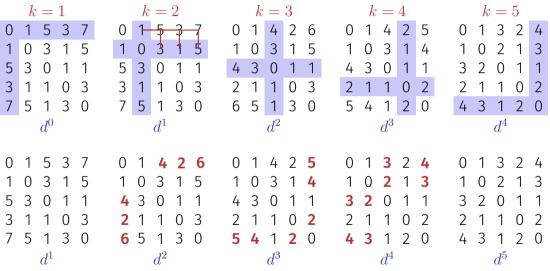
Input: Acyclic Graph G = (V, E, c)**Output:** Minimal weights of all paths d $d^0 \leftarrow c$ for $k \leftarrow 1$ to |V| do for $i \leftarrow 1$ to |V| do Runtime: $\Theta(|V|^3)$

Remark: Algorithm can be executed with a single matrix d (in place).

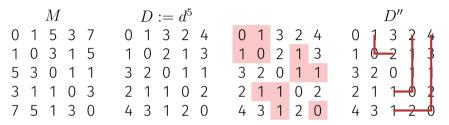


adjacency matrix M = c

	1	2	3	4	5
1	0	1	5	3	7
2	1	0	3	1	5
3	5	3	0	1	1
4	3	1	1	0	3
5	7	5	1	3	0



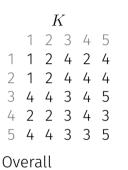
Shortest Path for each Pair?



Question: Can we use the computed matrix *D* to determine the shortest path between each pair of nodes?

Direct connections $i \rightarrow j$ where M[i, j] = D[i, j] (cf markings in D' above) Could try to run the algorithm backwards. Example $1 \rightarrow 3$ above in D''. Find, with decreasing k, the first fitting candidate. Complicated and inefficient. Memorize the best k in the algorithm for each node pair (i, j). Start with matrix of existing direct connections (edges)

k = 1 0 1 5 3 7 1 0 3 1 5 B 5 3 0 1 1 3 1 1 0 3 7 5 1 3 0	k = 2 0 1 4 2 6 1 0 3 1 5 4 3 0 1 1 2 1 1 0 3 6 5 1 3 0	k = 3 0 1 4 2 5 1 0 3 1 4 4 3 0 1 1 2 1 1 0 2 5 4 1 2 0	k = 4 0 1 3 2 4 1 0 2 1 3 3 2 0 1 1 2 1 1 0 2 4 3 1 2 0	k = 5 0 1 3 2 4 1 0 2 1 3 3 2 0 1 1 2 1 1 0 2 4 3 1 2 0
1 2 3 4 5 1 2 3 4 5 K 1 2 3 4 5 1 2 3 4 5 1 2 3 4 5 1 2 3 4 5	1 2 2 2 2 1 2 3 4 5 2 2 3 4 5	1 2 2 2 3 1 2 3 4 3 2 2 3 4 5 2 2 3 4 3 3 3 3 5	1 2 4 2 4 1 2 4 4 4 4 4 3 4 5 2 2 3 4 3 4 4 3 3 5	$\begin{array}{cccccccccccccccccccccccccccccccccccc$



How to read this matrix K? Example path $1 \rightarrow 5$:

- Path $1 \rightarrow 5$ goes via node 4.
- Path $1 \rightarrow 4$ goes via node 2.
- **Path** $4 \rightarrow 5$ goes via node 3.
- \blacksquare Paths $1 \rightarrow 2$ and $2 \rightarrow 4$ are direct.
- **•** Paths $4 \rightarrow 3$ and $3 \rightarrow 5$ are direct.

$$1 \xrightarrow{4} 5 \quad \Rightarrow \quad 1 \xrightarrow{2} 4 \xrightarrow{3} 5 \quad \Rightarrow \quad 1 \rightarrow 2 \rightarrow 4 \rightarrow 3 \rightarrow 5$$

Reconstruction via Recursion. Alternative? Store descenden in the algorithm

		k	=	1			k	=	2			k	=	3			k	=	4			k	=	5	
	0	1	5	3	7	0	1	4	2	6	0	1	4	2	5	0	1	3	2	4	0	1	3	2	4
	1	0	3	1	5	1	0	3	1	5	1	0	3	1	4	1	0	2	1	3	1	0	2	1	3
B	5	3	0	1	1	4	3	0	1	1	4	3	0	1	1	3	2	0	1	1	3	2	0	1	1
	3	1	1	0	3	2	1	1	0	3	2	1	1	0	2	2	1	1	0	2	2	1	1	0	2
	7	5	1	3	0	6	5	1	3	0	5	4	1	2	0	4	3	1	2	0	4	3	1	2	0
														\frown	X			k	\sim	4					
	1	2	3	4	5	1	2	2	2	2	1	2	2	2	2	1	2	2	2	2	1	2	2	2	2
	1	2	3	4	5	1	2	3	4	5	1	2	3	4	3	1	2	4	4	4	1	2	4	4	4
K	1	2	3	4	5	2	2	3	4	5	2	2	3	4	5	4	4	3	4	5	4	4	3	4	5
	1	2	3	4	5	2	2	3	4	5	2	2	3	4	3	2	2	3	4	3	2	2	3	4	3
	1	2	3	4	5	2	2	3	4	5	3	3	3	3	5	3	3	3	3	5	3	3	3	3	5

Comparison of the approaches

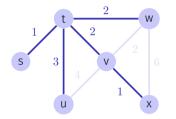
Algorithm			Runtime
Dijkstra (Heap)	$c_v \ge 0$	1:n	$\mathcal{O}(E \log V)$
Dijkstra (Fibonacci-Heap)	$c_v \ge 0$	1:n	$\mathcal{O}(E + V \log V)^{*}$
Bellman-Ford		1:n	$\mathcal{O}(E \cdot V)$
Floyd-Warshall		n:n	$\Theta(V ^3)$
Johnson		n:n	$\mathcal{O}(V \cdot E \cdot \log V)$
Johnson (Fibonacci-Heap)		n:n	$\mathcal{O}(V ^2 \log V + V \cdot E)^*$
*			

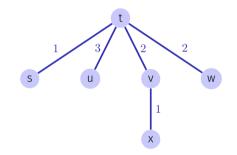
* amortized

Johnson (not explained this year) is better than Floyd-Warshall only for sparse graphs ($|E| \approx \Theta(|V|)$).

6.3 Minimum Spanning Trees

Minimum Spanning Trees





(Solution is not unique.)

Jarnik-Prim-Dijkstra Algorithm

- Finds a minimum spanning tree.
- Starts from a single node and grows.
- Uses a priority queue.
- Evaluates edges, not paths.

Algorithm Jarnik-Prim-Dijkstra(G)

Input: A connected, undirected graph G = (V, E) with weights w Output: A minimum spanning tree T

```
\begin{array}{l} \mbox{Initialize } T = \emptyset \\ \mbox{Choose arbitrary vertex } v_0 \mbox{ from } V \\ \mbox{while } V \neq \emptyset \mbox{ do} \\ \mbox{Choose edge } (u,v) \mbox{ with smallest weight such that } u \mbox{ is in } T \mbox{ and } v \mbox{ is in } V - T \\ \mbox{Add } v \mbox{ to } T \\ \mbox{Remove } v \mbox{ from } V \end{array}
```

return T

Differences from Dijkstra's Algorithm

- Jarnik-Prim-Dijkstra evaluates edges. Dijkstra evaluates paths.
- Jarnik-Prim-Dijkstra creates a minimum spanning tree. Dijkstra finds the shortest path.
- Jarnik-Prim-Dijkstra cannot handle negative weights. Dijkstra can under certain conditions.

MakeSet, Union, and Find

■ Make-Set(*i*): create a new set represented by *i*.

- Find(e): name of the set i that contains e.
- Union(i, j): union of the sets with names *i* and *j*.

In MST-Kruskal:

- Make-Set(i): New tree with i as root.
- Find(e): Find root of e
- Union(i, j): Union of the trees i and j.

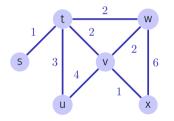
Algorithm MST-Kruskal(G)

Input: Weighted Graph G = (V, E, c)**Output:** Minimum spanning tree with edges A.

Sort edges by weight $c(e_1) \leq \ldots \leq c(e_m)$ $A \leftarrow \emptyset$ for k = 1 to |V| do MakeSet(k)for k = 1 to m do $(u,v) \leftarrow e_k$ if $Find(u) \neq Find(v)$ then Union(Find(u), Find(v)) $A \leftarrow A \cup e_k$

return (V, A, c)

Representation as array



s u v w 1 x

Index s t w v u x

Index s t u v w xParent t t t t v

Different kind of improvement

Link all nodes to the root when Find is called. Find(*i*):

```
\begin{array}{l} j \leftarrow i \\ \text{while } (p[i] \neq i) \text{ do } i \leftarrow p[i] \\ \text{while } (j \neq i) \text{ do } \\ \left| \begin{array}{c} t \leftarrow j \\ j \leftarrow p[j] \\ p[t] \leftarrow i \end{array} \right| \end{array}
```

return i

Cost: amortised nearly constant (inverse of the Ackermann-function).²

²We do not go into details here.

Running time of Kruskal's Algorithm

- Sorting of the edges: $\Theta(|E| \log |E|) = \Theta(|E| \log |V|)$.
- Initialisation of the Union-Find data structure $\Theta(|V|)$
- $|E| \times \text{Union}(\text{Find}(x), \text{Find}(y))$: $\mathcal{O}(|E| \log |E|) = \mathcal{O}(|E| \log |V|)$. Overal $\Theta(|E| \log |V|)$.

³because *G* is connected: $|V| \le |E| \le |V|^2$

7. Code-Expert Exercise

Code-Example

'Kruskal MST' on Code-Expert

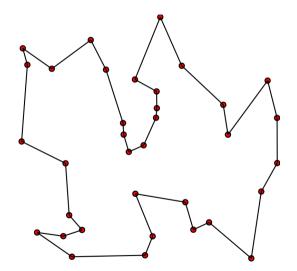
<u>8. TSP</u>

Problem

Given a map and list of cities, what is the shortest possible route that visits each city once and returns at the original city?

Mathematical model

On an undirected, weighted graph G, which cycle containing all of G's vertices has the lowest weight sum?



- The problem has no known polynomial-time solution.
- Many heuristic algorithms exists. They do not always return the optimal solution.

- The heuristic algorithm that you are asked to implement on CodeExpert (*The Travelling Student*) on CodeExpert uses an MST:
 - 1. Compute the minimum spanning tree M
 - 2. Make a depth first search on ${\cal M}$
- The algorithm is 2-approximate, meaning that the solution it generates has at most twice the cost of the optimal solution.
- The algorithm assumes a complete graph G = (V, E, c) that satisfies the triangle inequality: $c(v, w) \le c(v, x) + c(x, w) \forall v, w, x \in V$

9. Old Exam Question

Minimum Spanning Trees

Aufgabe 3: Minimum Spanning Trees (MST) (14P)

Sie haben den Auftrag erhalten, den Übersetzungsprozess für eine Dokumentation zu leiten. Leider wurden verschiedenen Abschnite der Dokumentation in verschiedenen Sprachen verfasst, so dasse sei ingesamt in verschiedne Sprachen gibt. Ihr Chef möchte, dass die gesamte Dokumentation in allen in Sprachen verfügbar ist.

Es stehen m verschiedene Übersetzer zur Verfügung, von denen jeder genau zwei der n Sprachen beherrscht und zwischen ihnen hin- und herühersetzen kann. leder Übersetzer hat strikt nositive Einstellungskosten. Leider haben Sie nicht genug Geld. um für jeder Sprachennaar einen Überretzer einzustellen. Stattdessen mössen Sie sich auf Übersetzerketten verlassen: Wenn Sie eineo Englisch Espanisisch Überretzer und einen Französisch-Snanisch-Übersetzer einstellen können Sie die Dokumentation auch zwischen Englisch und Spanisch übersetzen. Ihr Ziel ist es, sins Counse une Oberretzern mit minimalen Kosten zu finden, die eine Übersetzung zwischen allen n Sprachen ermöglicht.

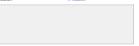
(a) Modellieren Sie das Problem als ein Problem des minimalen Spannbaums. Beschreiben Sie den Graphen (d.h. die Menge der Knoten, die Menge der Kanten und die Gewichte) in Worten.

You have been hired to manage the translation process for some documentation. Unfortunately, different sections of the documentation were written in different languages in total. Your are n different languages in total. Your boss wants the entire documentation to be available in al in languages.

There are m different translators for hire. and each of them knows exactly two of the n languages and can translate back and forth between them. Each translator has a strictly position hiring cost. Unfortunately, you don't have ensuch money to hire one translator for each nale of Janeusges Justead you'll need to rely on chains of translators: if you hire an English-French translator and a French-Spanish translator, you'll also he able to translate the documentation between English and Spanish. Your goal is to find a pat of translators of minimal cost that allows for translation between all n Janeusees.

Model the problem as a minimum spanning tree problem. Describe the graph (i.e. the set of vertices, the set of edges and the weights) in words. (b) Nennen Sie einen Algorithmus aus der Vorlesung zur Lösung des Problems des minimalen Spannhaums. Nennen Sie den Namen des Algorithmus und seine Laufzeit als Funktion von Anzahl Knoten n und Anzahl Kanten m in G-Notation.

Give an algorithm from the lecture to solve the minimum spanning tree problem. State the name of the algorithm and its running time in terms of number of nodes n and number of edges m in 0-notation.



(c) Führen Sie den oben gewählten Algorithmus auf dem folgenden Graphen aus. Geben Sie den Namen des Algorithmus erneut an und geben Sie bei jedem Schritt an, welche Kante zum MST hinzugefögt wird.

Run the algorithm selected above on the following graph instance. Give the name of the algorithm again and indicate at each step which edge you are adding to the MST.





Sunnose that additionally to the nlanguages, your boss also wants the whole documentation translated in Swiss-German (which was not part of the n original languages). You have at your disposal n additional translators (translating hotogen Suice-German and each of the n original languages), each of them having a different positive hiring cost. You had already computed the minimum spanning tree of the n original languages when your boss asked for this extra requirement, so you now need to find the minimum spanning tree of the n + 1 Janguages. Can you simply add the cheapest Swiss-German translator to your original spanning tree ? Justify your 300000



Minimum Spanning Trees - Solution

Aufgabe 3: Minimum Spanning Trees (MST) (14P)

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(a) Modellieren Sie das Problem als ein Problem des minimalen Spannbaums. Beschreiben Sie den Graphen (d.h. die Menge der Knoten, die Menge der Kanten und die Gewichte) in Worten.

> We can model the problem as an MST problem on an undirected graph whose vertices are given by the n languages, and two vertices are connected by an edge if there is a translator inoving the two corresponding languages. The weight of an edge is the hiring cost of the corresponding translator.

Janeusees.

(b) Nennen Sie einen Algorithmus aus der Voriesung zur Lösung des Problems des minimaler Spannbaums. Hennen Sie den Namen des Algorithmus und seine Laufzeit als Funktion von Anzahl Knoten n und Anzahl Kanten m in O-Notation. Give an algorithm from the lecture to solve the minimum spanning tree problem. State the name of the algorithm and its running time in terms of number of nodes n and number of edges m in 0-notation.

Kruskal's algorithm (runtime: $\Theta(m \log n)$). Prim's algorithm (runtime: $\Theta(m + n \log n)$).

(c) F
ühren Sie den oben gew
ählten Algorithmus auf dem folgenden Graphen aus. Geben Sie den Namen des Algorithmus erneut an und geben Sie bei jedern Schritt an, welche Kante zum MST hinzueeflast wird.

Run the algorithm selected above on the following graph instance. Give the name of the algorithm again and indicate at each step which edge you are adding to the MST.



Here are the order in which the edges are added to the (unique) NBT for the different algorithms. Krunkait* algorithm: (M, ef, ef, ed, ac, ef, ef, ef, edges)Prim's algorithm (started at vertex a) : ad, bd, ac, ef, ef, ef, edges)Prim's algorithm (started at vertex b or $d) : M_1 ad, ac, ef, ef, ef, edges)$

Prim's algorithm (started at vertex c): cf, cf, ac, ad, bd.
Prim's algorithm (started at vertex c or f): cf, cf, ac, ad, bd.

(d) Nehmen wir an dass Ihr Chef zusätzlich zu den n Sprachen die gesamte Dokumentation auch auf Schwiizerdütsch übersetzt haben möchte (was nicht zu den n Originalsprachen gehörte). Es stehen n zusätzliche Übersetzer zur Verfügung (die zwischen Schwitzerdütsch und inder der n Originalsprachen übergetzen), von denen ieder unterschiedliche positive Einstellungskosten hat. Sie hatten bereits den minimalen Spannbaum für die n Originalsorathen herechnet, als Ihr Chef diese zusätzliche Anforderung stellte, also müssen Sie nun den minimalen Spannbaum für die n + 1 Sprachen finden. Können Sie einfach den günstigsten Schwüzerdütsch-Übersetzer zum urserünzlichen Spannbaum hinzufügen? Begründen Sie Ihre Antwort.

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General Questions?

Don't forget!

Next Week's Session

- Wed 8th May
- 16 18
- CHN G 42

See you next time

Have a nice week!