

Analysis Übungsstunde 7

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aber!



This Serie covers a new topic: the discrete Fourier transform (DFT) and the fast Fourier transform (FFT). This topic has not been taught in the last few years, so feel free to ask if you have a question.

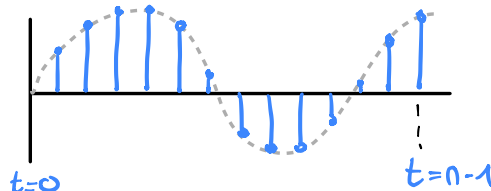
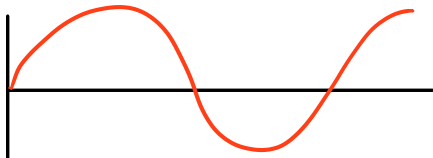
I'll have to talk with Prof. Iozzi to give you a precise answer. But I guess it was more about providing them insight into the DFT and FFT. The multiple-choice question might have a short question about the DFT or FFT in the exam (but I'm not even sure), but I don't think there'll be an open question about this topic.

Organisatorisches: Nächste Woche 7.11 keine Übungsstunde
→ Ich würde Recording auf Youtube laden

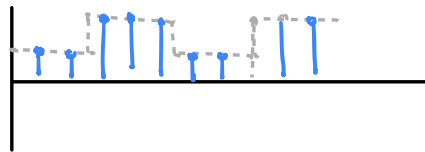
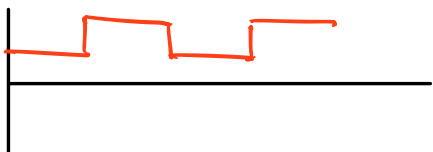
Discrete time (man kann nur an einzelnen punkten messen)

Continuous time

Discrete time



Nicht für jeden Zeitwert definiert



Sampling time: wie oft gemessen wird

$$t_0 = 0$$

$$t_1 = 1 \cdot \frac{2\pi}{n}$$

⋮

$$t_{n-1} = (n-1) \frac{2\pi}{n}$$

$$t_j = j \frac{2\pi}{n} \quad j \in [0, n-1]$$

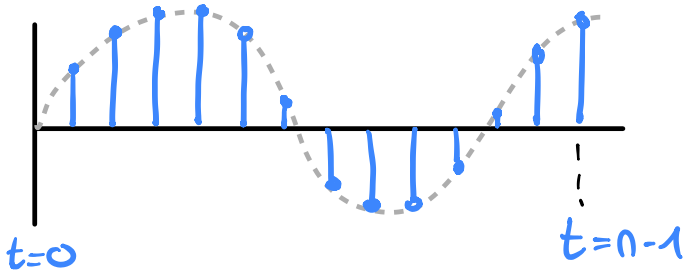
▷ Integrale werden zu Summen

▷ Zeit von 0 bis n-1 (das n-te Sample)

$$f_j = f\left(j \frac{2\pi}{n}\right) \quad t_j = j \frac{2\pi}{n}$$

⇒ gute Videos hier: DFT <https://youtu.be/nl9TZanwbBk?si=b2lpDKE8KJ55uKzu>
(Steve Brunton) FFT https://youtu.be/toj_loCQE-4?si=2iikxfd9X7aVwSzn

Discrete Fourier Transform



$$\underline{F} := \begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_{n-1} \end{pmatrix} \quad \underline{C} := \begin{pmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \end{pmatrix}$$

endliche Fouriers Serie

Vektor von Datenpunkten

$$f(t) = c_0 + c_1 e^{it} + c_2 e^{2it} + \dots + c_{n-1} e^{(n-1)it} =$$

$$\text{für jeden sample Punkt } t_j: f_j = \sum_{k=0}^{n-1} c_k e^{kit_j}$$

$$t_j = j \frac{2\pi}{n}$$

$$\triangleright f_j = \sum_{k=0}^{n-1} c_k \cdot e^{kit_j} = \sum_{k=0}^{n-1} c_k \cdot \underbrace{\omega_n^{kj}}_{\mu_n} \quad \forall j \in [0, n-1]$$

$\omega_n = e^{\frac{2\pi i}{n}}$

$$\triangleright \omega_n = e^{\frac{2\pi i}{n}}$$

$$\triangleright c_k = \frac{1}{n} \sum_{j=0}^{n-1} e^{-kit_j} \cdot f_j = \frac{1}{n} \sum_{j=0}^{n-1} \omega_n^{-kj} \cdot f_j \quad \forall k \in [0, n-1] \Rightarrow \text{schreibe als Matrix}$$

$= \mu_n^{-1}$

(inverse)

$$F = \mu_n C$$

$\Leftrightarrow$

$$C = \mu_n^{-1} F$$

$$\begin{pmatrix} \hat{f}_0 \\ \hat{f}_1 \\ \hat{f}_2 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix} = \underbrace{\mu_n = (\omega_n^{hk})_{h,k=0 \dots n-1}}_{\substack{1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^2 & \dots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \dots & \omega_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \dots & \omega_n^{(n-1)^2} }} \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{pmatrix} \quad \bigg| \quad \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{pmatrix} = \underbrace{\frac{1}{n} \mu_n^{-1} = \frac{1}{n} (\omega_n^{-hk})_{h,k=0 \dots n-1}}_{\substack{1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^{-2} & \dots & \omega_n^{-(n-1)} \\ 1 & \omega_n^2 & \omega_n^{-4} & \dots & \omega_n^{-2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{-2(n-1)} & \dots & \omega_n^{-(n-1)^2} }} \begin{pmatrix} \hat{f}_0 \\ \hat{f}_1 \\ \hat{f}_2 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix}$$

normalisation

Vgl: continuous time

$$\hat{f} = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) \cdot e^{-i\omega t} dt$$

$$f(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{g}(\omega) \cdot e^{+i\omega t} d\omega$$

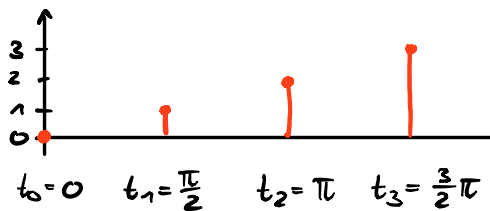
discrete time

$$f_j = \sum_{k=0}^{n-1} c_k \cdot e^{kit_j}$$

$\uparrow$
k-te frequenz coeff

$$c_k = \frac{1}{n} \sum_{j=0}^{n-1} e^{-kit_j} \cdot f_j$$

Bsp: sample:



finde trigonometrische representation

$$t_j = \frac{2\pi}{n} j$$

#messungen = 4

$n=4$

$$F = \begin{pmatrix} 0 \\ 1 \\ 2 \\ 3 \end{pmatrix} \quad C = \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix}$$

$$f(0)=0, f(\frac{2\pi}{N})=1, f(2\frac{2\pi}{N})=2, f(3\frac{2\pi}{N})=3$$

$$f(t) = c_0 + c_1 e^{it} + c_2 e^{2it} + \dots + c_{n-1} e^{(n-1)it} \quad // \text{ suche coeff } c$$

$$= c_0 + c_1 e^{it} + c_2 e^{2it} + c_3 e^{3it}$$

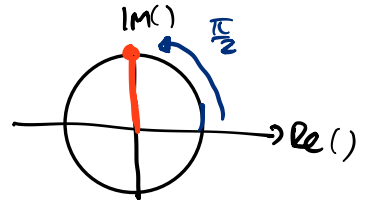
$$C = M_n^{-1} F$$

$$M_n^{-1} = \frac{1}{n} (w_n^{-hk})_{h,k=0,\dots,n-1}$$

$$= \frac{1}{n} \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & w_n & w_n^2 & \dots & w_n^{-(n-1)} \\ 1 & w_n^2 & w_n^4 & \dots & w_n^{-2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w_n^{-(n-1)} & w_n^{-2(n-1)} & \dots & w_n^{-(n-1)^2} \end{pmatrix}$$

$$w_n = e^{\frac{2\pi i}{n}}$$

$$w_4 = e^{\frac{2\pi i}{4}} = e^{i\frac{\pi}{2}} = i$$



$$M_4^{-1} = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & w_4 & w_4^2 & w_4^3 \\ 1 & w_4^2 & w_4^4 & w_4^6 \\ 1 & w_4^3 & w_4^6 & w_4^9 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -i & -1 & +i \\ 1 & -1 & 1 & -1 \\ 1 & i & -1 & -i \end{pmatrix}$$

$$\begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -i & -1 & +i \\ 1 & -1 & 1 & -1 \\ 1 & i & -1 & -i \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} \frac{3}{2} \\ (-1+i)/2 \\ -\frac{1}{2} \\ (-1-i)/2 \end{pmatrix} = C$$

brauche Eulers form:

$$\sin(x) = \frac{1}{2i} (e^{ix} - e^{-ix})$$

$$\cos(x) = \frac{1}{2} (e^{ix} + e^{-ix})$$

$$f(t) = \frac{1}{2} \left(\underbrace{3}_{c_0} + \underbrace{(-1+i)}_{c_1} e^{it} - \underbrace{1}_{c_2} e^{2it} - \underbrace{(1+i)}_{c_3} e^{3it} \right)$$

$$f(t) = \underbrace{\frac{3}{2} - \frac{1}{2} \cos t - \frac{1}{2} \cos 2t - \frac{1}{2} \cos 3t - \frac{1}{2} \sin t + \frac{1}{2} \sin 3t}_{\text{Re()}} + i \underbrace{\left(\frac{1}{2} \cos t - \frac{1}{2} \cos 3t - \frac{1}{2} \sin t - \frac{1}{2} \sin 2t - \frac{1}{2} \sin 3t \right)}_{\text{Im()}}$$

▷ überprüfen: für $t=0, \frac{\pi}{2}, \pi, \frac{3}{2}\pi$ würde funktion 0, 1, 2, 3 werden

▷ da f nur die Reellen werte bei unseren sample points, nimm nur Realteil

$$\Rightarrow \text{Lösung} = \text{Re}(f(t)) = \frac{3}{2} - \frac{1}{2} \cos t - \frac{1}{2} \cos 2t - \frac{1}{2} \cos 3t - \frac{1}{2} \sin t + \frac{1}{2} \sin 3t$$

$\Rightarrow n$ Reihen, n Spalten $\rightarrow O(n^2)$

Fast Fourier Transform (FFT)

Discrete Fourier transform $O(n^2)$

Fast Fourier Transform $O(n \log(n))$!

- ▷ Denoise Data
- ▷ Analysis of Data
- ▷ Compression of audio & Images

DFT

$$N = 10^3$$

$$N = 10^6$$

$$N^2 = 10^6$$

$$N^2 = 10^{12}$$

FFT

$$N \log_2 N \approx 10^4$$

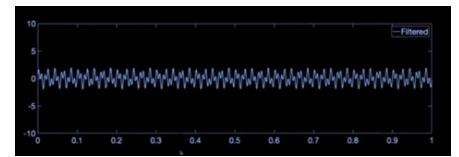
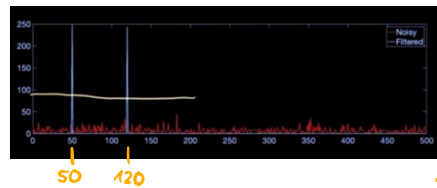
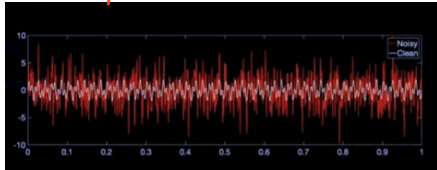
$$N \log_2 N \approx 2 \times 10^7$$

100 times smaller
50,000 times smaller

$$\begin{pmatrix} \hat{f}_0 \\ \hat{f}_1 \\ \hat{f}_2 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^2 & \dots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \dots & \omega_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \dots & \omega_n^{(n-1)^2} \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{pmatrix}$$

noisy Data

FFT
→



$$\sin(2\pi \cdot 50t) + \sin(2\pi \cdot 120t)$$

bsp $n = 2^{10} = 1024$

cut

$$\Rightarrow \underline{F} = \underline{M}_n \underline{C}$$

$F = M_{1024} \cdot C$ aufteilen von M -Matrix: gerade & ungerade reihen

$$F = \begin{bmatrix} \underline{I}_{512} & -\underline{D}_{512} \\ \underline{I}_{512} & \underline{D}_{512} \end{bmatrix} \begin{bmatrix} \underline{M}_{512} & \underline{O} \\ \underline{O} & \underline{M}_{512} \end{bmatrix} \begin{pmatrix} c_{\text{even}} \\ c_{\text{odd}} \end{pmatrix}$$

! def $f^{(o)} := f_{\text{odd}}$
 $f^{(e)} := f_{\text{even}}$
(same for c)

$\underline{D}_{512} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & \omega & 0 & \dots & 0 \\ 0 & 0 & \omega^2 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \omega^{511} \end{bmatrix}$

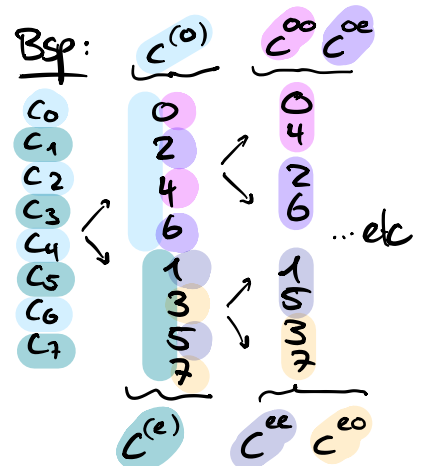
einfach zum rechnen für computer: Diagonalmatrizen & Nulleinträge

weils aufteilen $M_{1024} \rightarrow M_{512} \rightarrow M_{256} \rightarrow M_{128} \dots M_4 \rightarrow M_2$!!

$$\Rightarrow O(n \log(n))$$

→ code: $\hat{f} = \text{fft}(f, n)$

$$T_n := \begin{bmatrix} [\mu_2] & 0 & 0 & \dots & 0 \\ 0 & [\mu_2] & 0 & \dots & 0 \\ 0 & 0 & [\mu_2] & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & [\mu_2] \end{bmatrix}$$



Formeln für Serie 7:

$$M = \frac{n}{2}$$

$$c^{(o)} = \begin{pmatrix} c_0^{(o)} \\ c_2^{(o)} \end{pmatrix} = M_2^{-1} f^{(o)}$$

$$c^{(e)} = \begin{pmatrix} c_0^{(e)} \\ c_2^{(e)} \end{pmatrix} \cdot M_2^{-1} f^{(e)}$$

$$k < M:$$

$$c_k = \frac{1}{2} (c_k^{(o)} + \omega_N^k c_k^{(e)})$$

$$k \geq M$$

$$c_{k+M} = \frac{1}{2} (c_k^{(o)} - \omega_N^k c_k^{(e)})$$

Bsp mit FFT

finde trigonometrische representation

3. Fast Fourier Transform (FFT)

Compute the Fast Fourier Transform (FFT) of the same function given in exercise 1. Check that you get the same result.

Steps:

- 1) Find the value of w_M , where $M = \frac{N}{2}$.
- 2) Compute the even and odd coefficients $C^{(o)}$ and $C^{(e)}$ using the formula

$$C^{(o)} = \begin{bmatrix} c_0^{(o)} \\ c_2^{(o)} \end{bmatrix} = M_2^{-1} f^{(o)}, \quad \text{and} \quad C^{(e)} = \begin{bmatrix} c_0^{(e)} \\ c_2^{(e)} \end{bmatrix} = M_2^{-1} f^{(e)}$$

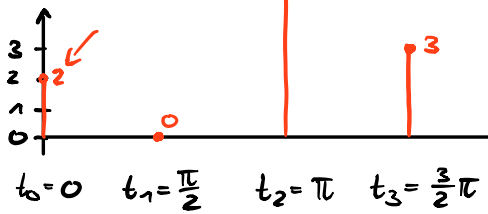
- 3) Find the value of w_N .

- 4) Compute the coefficient c_k using the formulas for $k < M$

$$c_k = \frac{1}{2} (c_k^{(o)} + w_N^k c_k^{(e)})$$

And for the coefficient c_k with $k \geq M$,

$$c_k = \frac{1}{2} (c_k^{(o)} - w_N^k c_k^{(e)})$$



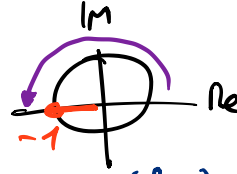
$$t_j = \frac{2\pi}{N} j$$

$$\# \text{Messungen} = 4 \quad N=4$$

$$\rightarrow \omega_M = ? \rightarrow M = \frac{N}{2} = \frac{4}{2} = 2$$

$$\omega_M = e^{\frac{2\pi i}{2}} = e^{\pi i} = -1$$

$$C = \frac{1}{N} M^{-1} F, \quad F = \begin{pmatrix} 2 \\ 0 \\ 6 \\ 3 \end{pmatrix} = \begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \end{pmatrix}$$



$$f^{(o)} = \begin{pmatrix} f_0 \\ f_2 \end{pmatrix} \\ f^{(e)} = \begin{pmatrix} f_1 \\ f_3 \end{pmatrix}$$

Anstatt 4x4 Matrix nun zwei einzelne 2x2

$$C^{(o)} = M_2^{-1} f^{(o)}$$

$$\begin{pmatrix} c_0^{(o)} \\ c_1^{(o)} \end{pmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{pmatrix} f_0 \\ f_2 \end{pmatrix}$$

$$\begin{pmatrix} c_0^{(o)} \\ c_1^{(o)} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} f_0 + f_2 \\ f_0 - f_2 \end{pmatrix}$$

$$C^{(e)} = M_2^{-1} f^{(e)}$$

$$\begin{pmatrix} c_0^{(e)} \\ c_1^{(e)} \end{pmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{pmatrix} f_1 \\ f_3 \end{pmatrix}$$

$$\begin{pmatrix} c_0^{(e)} \\ c_1^{(e)} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} f_1 + f_3 \\ f_1 - f_3 \end{pmatrix}$$

$$\text{since } N=4 \rightarrow \omega_N = e^{\frac{2\pi i}{4}} = e^{i\frac{\pi}{2}} = i$$

$$k=0,1,2,3$$

$$k < M: \quad k=0,1$$

$$k \geq M: \quad k=2,3$$

$$c_k = \frac{1}{2} (c_k^{(o)} + \omega_N^k c_k^{(e)})$$

$$c_{k+M} = \frac{1}{2} (c_k^{(o)} - \omega_N^k c_k^{(e)})$$

$$c_0 = \frac{1}{2} (c_0^{(o)} + i^0 c_0^{(e)}) \\ = \frac{1}{4} (f_0 + f_1 + f_2 + f_3)$$

$$c_2 = \frac{1}{2} (c_0^{(o)} - i^0 c_0^{(e)}) \\ = \frac{1}{4} (f_0 - f_1 + f_2 - f_3)$$

$$c_1 = \frac{1}{2} (c_1^{(o)} + i^1 c_1^{(e)}) \\ = \frac{1}{4} (f_0 - i f_1 - f_2 + i f_3)$$

$$c_3 = \frac{1}{2} (c_1^{(o)} - i^1 c_1^{(e)}) \\ = \frac{1}{4} (f_0 + i f_1 - f_2 - i f_3)$$

brauche Eulers form:

$$\sin(x) = \frac{1}{2i} (e^{ix} - e^{-ix})$$

$$\cos(x) = \frac{1}{2} (e^{ix} + e^{-ix})$$

$$\begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 6 \\ 3 \end{pmatrix} \rightarrow \text{einsetzen}$$

$$c_0 = \frac{11}{4} \\ c_1 = \frac{-4+3i}{4}$$

$$c_2 = \frac{5}{4} \\ c_3 = \frac{-4-3i}{4}$$

$$f(t) = c_0 + c_1 e^{it} + c_2 e^{2it} + c_3 e^{3it}$$

$$f(t) = \frac{1}{4} (11 - 4 \cos(t) - 3 \sin(t) + 5 \cos(2t) - 4 \cos(3t) + 3 \sin(3t)) + \frac{i}{4} (-4 \sin(t) + 3 \cos(t) + 5 \sin(2t) - 4 \sin(3t) - 3 \cos(3t))$$

Re()

Im()