

Analysis Übungsstunde 7

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aber!



This Serie covers a new topic: the discrete Fourier transform (DFT) and the fast Fourier transform (FFT). This topic has not been taught in the last few years, so feel free to ask if you have a question.

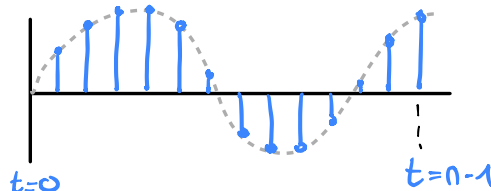
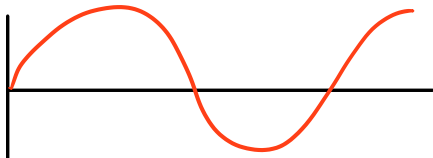
I'll have to talk with Prof. Iozzi to give you a precise answer. But I guess it was more about providing them insight into the DFT and FFT. The multiple-choice question might have a short question about the DFT or FFT in the exam (but I'm not even sure), but I don't think there'll be an open question about this topic.

Organisatorisches: Nächste Woche 7.11 keine Übungsstunde
→ Ich würde Recording auf Youtube laden

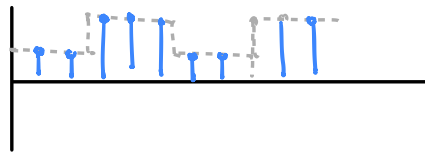
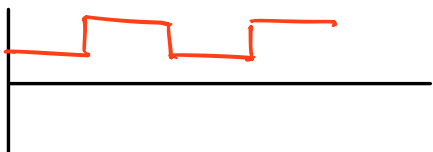
Discrete time (man kann nur an einzelnen punkten messen)

Continuous time

Discrete time



Nicht für jeden Zeitwert definiert



Sampling time: wie oft gemessen wird

$$t_0 =$$

$$t_1 =$$

$$\vdots$$

$$t_{n-1} =$$

$$j \in [0, n-1]$$

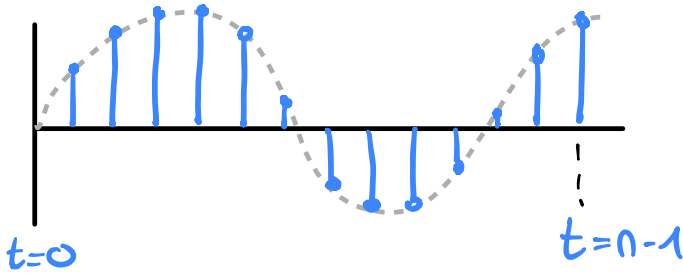
▷ Integrale werden zu Summen

▷ Zeit von 0 bis $n-1$ (das n -te Sample)

$$f_j = f\left(\right) \quad t_j = j \frac{2\pi}{N}$$

⇒ gute Videos hier: DFT <https://youtu.be/nl9TZanwbBk?si=b2lpDKE8KJ55uKzu>
(Steve Brunton) FFT https://youtu.be/toj_loCQE-4?si=2iikxfd9X7aVwSzn

Discrete Fourier Transform



$$\underline{F} := \begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_{n-1} \end{pmatrix} \quad \underline{C} := \begin{pmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \end{pmatrix}$$

endliche Fouriers Serie

$$f(t) = c_0 + c_1 e^{it} + c_2 e^{2it} + \dots + c_{n-1} e^{(n-1)it} =$$

$$\text{für jeden sample Punkt } t_j: f_j = \sum_{k=0}^{n-1} c_k e^{kit_j}$$

Vektor von Datenpunkten

$$t_j = j \frac{2\pi}{n}$$

$$\triangleright f_j = \sum_{k=0}^{n-1} c_k \cdot e^{kit_j} = \sum_{k=0}^{n-1} c_k \cdot \underbrace{\omega_n^{kj}}_{\mu_n} \quad \forall j \in [0, n-1]$$

$\omega_n = e^{\frac{2\pi i}{n}}$

$$\triangleright \omega_n = e^{\frac{2\pi i}{n}}$$

$$\triangleright c_k = \frac{1}{n} \sum_{j=0}^{n-1} e^{-kit_j} \cdot f_j = \frac{1}{n} \sum_{j=0}^{n-1} \omega_n^{-kj} \cdot f_j \quad \forall k \in [0, n-1] \Rightarrow \text{schreibe als Matrix}$$

$= \mu_n^{-1}$

(inverse)

$$F = \mu_n C$$

$\Leftrightarrow$

$$C = \mu_n^{-1} F$$

$$\begin{pmatrix} \hat{f}_0 \\ \hat{f}_1 \\ \hat{f}_2 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix} = \underbrace{\mu_n = (\omega_n^{hk})_{h,k=0 \dots n-1}}_{\substack{1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^2 & \dots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \dots & \omega_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \dots & \omega_n^{(n-1)^2} }} \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{pmatrix} \quad \bigg| \quad \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{pmatrix} = \underbrace{\frac{1}{n} \mu_n^{-1} = \frac{1}{n} (\omega_n^{-hk})_{h,k=0 \dots n-1}}_{\substack{1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^{-2} & \dots & \omega_n^{-(n-1)} \\ 1 & \omega_n^2 & \omega_n^{-4} & \dots & \omega_n^{-2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{-2(n-1)} & \dots & \omega_n^{-(n-1)^2} }} \begin{pmatrix} \hat{f}_0 \\ \hat{f}_1 \\ \hat{f}_2 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix}$$

normalisation

Vgl: continuous time

$$\hat{f} = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) \cdot e^{-i\omega t} dt$$

$$f(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{g}(\omega) \cdot e^{+i\omega t} d\omega$$

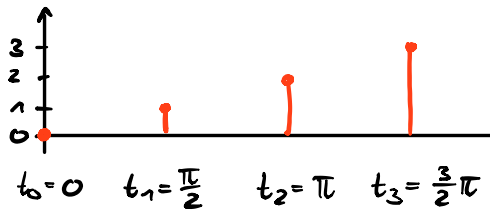
discrete time

$$f_j = \sum_{k=0}^{n-1} c_k \cdot e^{kit_j}$$

$\uparrow$
k-te frequenz coeff

$$c_k = \frac{1}{n} \sum_{j=0}^{n-1} e^{-kit_j} \cdot f_j$$

Bsp: sample:



finde trigonometrische representation

$$t_j = \frac{2\pi}{n} j$$

#messungen =

$$F = \begin{pmatrix} \end{pmatrix} \quad C = \begin{pmatrix} \end{pmatrix}$$

$$f(0) = 0, f\left(\frac{2\pi}{n}\right) = 1, f\left(2\frac{2\pi}{n}\right) = 2, f\left(3\frac{2\pi}{n}\right) = 3$$

$$f(t) = c_0 + c_1 e^{it} + c_2 e^{2it} + \dots + c_{n-1} e^{(n-1)it} \quad // \text{ suche coeff } c$$

$$= c_0 + c_1 e^{it} + c_2 e^{2it} + c_3 e^{3it}$$

$$C = M_n^{-1} F$$

$$M_n^{-1} := \frac{1}{n} (w_n^{-hk})_{h,k=0,\dots,n-1}$$

$$= \frac{1}{n} \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & w_n & w_n^{-2} & \dots & w_n^{-(n-1)} \\ 1 & w_n^{-2} & w_n^{-4} & \dots & w_n^{-2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w_n^{-(n-1)} & w_n^{-2(n-1)} & \dots & w_n^{-(n-1)^2} \end{pmatrix}$$

$$w_n = e^{\frac{2\pi i}{n}}$$

$$M_4^{-1} = \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & & & \\ 1 & & & \\ 1 & & & \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & & & \\ 1 & & & \\ 1 & & & \end{bmatrix}$$

$$\begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{bmatrix} \end{bmatrix} \cdot \begin{pmatrix} \end{pmatrix} = \begin{pmatrix} \end{pmatrix}$$

brauche Eulers form:

$$f(t) =$$

↓

$$f(t) = \frac{3}{2} - \frac{1}{2} \cos t - \frac{1}{2} \cos 2t - \frac{1}{2} \cos 3t - \frac{1}{2} \sin t + \frac{1}{2} \sin 3t + i \left(\frac{1}{2} \cos t - \frac{1}{2} \cos 3t - \frac{1}{2} \sin t - \frac{1}{2} \sin 2t - \frac{1}{2} \sin 3t \right)$$

▷ überprüfen: für $t = 0, \frac{\pi}{2}, \pi, \frac{3}{2}\pi$ würde funktion 0, 1, 2, 3 werden

▷ da f nur die Reellen werte bei unseren sample points, nimm nur Realteil

$$\Rightarrow \text{Lösung} = \text{Re}(f(t)) = \frac{3}{2} - \frac{1}{2} \cos t - \frac{1}{2} \cos 2t - \frac{1}{2} \cos 3t - \frac{1}{2} \sin t + \frac{1}{2} \sin 3t$$

$$\Rightarrow n \text{ Reihen, } n \text{ Spalten} \rightarrow O(n^2)$$

Fast Fourier Transform (FFT)

Discrete Fourier transform $O(n^2)$

Fast Fourier Transform $O(n \log(n))$!

- ▷ Denoise Data
- ▷ Analysis of Data
- ▷ Compression of audio & Images

DFT

$$N = 10^3$$

$$N = 10^6$$

$$N^2 = 10^6$$

$$N^2 = 10^{12}$$

FFT

$$N \log_2 N \approx 10^4$$

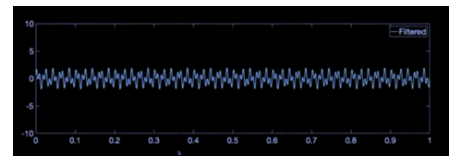
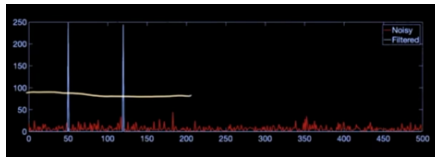
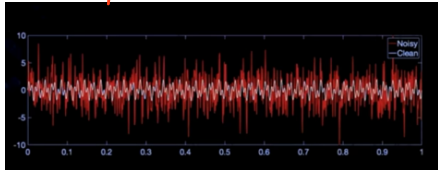
$$N \log_2 N \approx 2 \times 10^7$$

100 times smaller
50,000 times smaller

$$\begin{pmatrix} \hat{f}_0 \\ \hat{f}_1 \\ \hat{f}_2 \\ \vdots \\ \hat{f}_{n-1} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^2 & \dots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \dots & \omega_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \dots & \omega_n^{(n-1)^2} \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{pmatrix}$$

noisy Data

FFT
→



bsp $n = 2^{10} = 1024$

cut

$$\Rightarrow \underline{F} = \underline{M}_n \underline{C}$$

$F = M_{1024} \cdot C$ aufteilen von M -Matrix: gerade & ungerade reihen

$$F = \begin{bmatrix} \underline{I}_{512} & -\underline{D}_{512} \\ \underline{I}_{512} & \underline{D}_{512} \end{bmatrix} \begin{bmatrix} \underline{M}_{512} & \underline{O} \\ \underline{O} & \underline{M}_{512} \end{bmatrix} \begin{pmatrix} c_{\text{even}} \\ c_{\text{odd}} \end{pmatrix}$$

def $f^{(o)} := f_{\text{odd}}$
 $f^{(e)} := f_{\text{even}}$
(same for c)

$\underline{D}_{512} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & \omega & 0 & \dots & 0 \\ 0 & 0 & \omega^2 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \omega^{511} \end{bmatrix}$

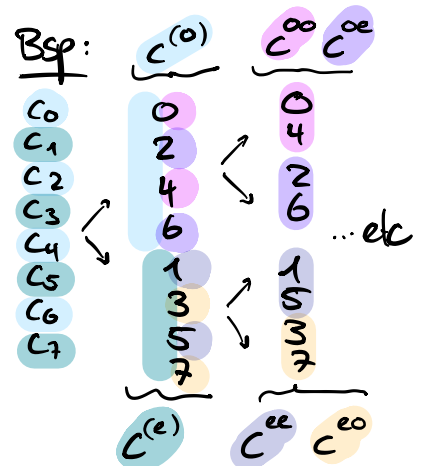
einfach zum rechnen für computer: Diagonalmatrizen & Nulleinträge

weils aufteilen $M_{1024} \rightarrow M_{512} \rightarrow M_{256} \rightarrow M_{128} \dots M_4 \rightarrow M_2$!!

$$\Rightarrow O(n \log(n))$$

→ code: $\hat{f} = \text{fft}(f, n)$

$$T_n := \begin{bmatrix} [M_2] & 0 & 0 & \dots & 0 \\ 0 & [M_2] & 0 & \dots & 0 \\ 0 & 0 & [M_2] & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & [M_2] \end{bmatrix}$$



Formeln für Serie 7:

$$M = \frac{n}{2}$$

$$c^{(o)} = \begin{pmatrix} c_0^{(o)} \\ c_2^{(o)} \end{pmatrix} = M_2^{-1} f^{(o)}$$

$$c^{(e)} = \begin{pmatrix} c_0^{(e)} \\ c_2^{(e)} \end{pmatrix} = M_2^{-1} f^{(e)}$$

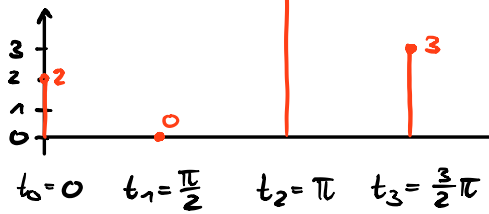
$k < M$:

$$c_k = \frac{1}{2} (c_k^{(o)} + \omega_N^k c_k^{(e)})$$

$k \geq M$

$$c_{k+M} = \frac{1}{2} (c_k^{(o)} - \omega_N^k c_k^{(e)})$$

Bsp mit FFT



finde trigonometrische representation

$$t_j = \frac{2\pi}{N} j$$

messungen =

3. Fast Fourier Transform (FFT)

Compute the Fast Fourier Transform (FFT) of the same function given in exercise 1. Check that you get the same result.

Steps:

1) Find the value of w_N , where $M = \frac{N}{2}$.

2) Compute the even and odd coefficients $C^{(o)}$ and $C^{(e)}$ using the formula

$$C^{(o)} = \begin{bmatrix} c_0^{(o)} \\ c_2^{(o)} \end{bmatrix} = M_2^{-1} f^{(o)}, \quad \text{and} \quad C^{(e)} = \begin{bmatrix} c_0^{(e)} \\ c_2^{(e)} \end{bmatrix} = M_2^{-1} f^{(e)}$$

3) Find the value of w_N .

4) Compute the coefficient c_k using the formulas for $k < M$

$$c_k = \frac{1}{2} (c_k^{(o)} + w_N^k c_k^{(e)})$$

And for the coefficient c_k with $k \geq M$,

$$c_k = \frac{1}{2} (c_k^{(o)} - w_N^k c_k^{(e)})$$

$$\rightarrow \omega_M = ? \rightarrow$$

$$\omega_M =$$

$$C = \frac{1}{N} M_M^{-1} F, \quad F = \begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \end{pmatrix} = \begin{pmatrix} f^{(o)} \\ f^{(e)} \end{pmatrix}$$

Anstatt 4x4 Matrix nun zwei einzelne 2x2

$$C^{(o)} = M_2^{-1} \cdot f^{(o)}$$

$$\begin{pmatrix} c_0^{(o)} \\ c_2^{(o)} \end{pmatrix} = \begin{bmatrix} & \\ & \end{bmatrix} \begin{pmatrix} \\ \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} & \\ & \end{pmatrix}$$

$$C^{(e)} = M_2^{-1} \cdot f^{(e)}$$

$$\begin{pmatrix} c_0^{(e)} \\ c_2^{(e)} \end{pmatrix} = \begin{bmatrix} & \\ & \end{bmatrix} \begin{pmatrix} \\ \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} & \\ & \end{pmatrix}$$

since $N=4 \rightarrow \omega_N = e^{\frac{2\pi i}{4}} = e^{i\frac{\pi}{2}} = i$

$$k=0,1,2,3$$

$k < M$: $k=0,1$

$k \geq M$: $k=2,3$

$$c_k = \frac{1}{2} (c_k^{(o)} + \omega_N^k c_k^{(e)})$$

$$c_{k+M} = \frac{1}{2} (c_k^{(o)} - \omega_N^k c_k^{(e)})$$

$$c_0 =$$

$$= \frac{1}{4} (f_0 + f_1 + f_2 + f_3)$$

$$c_2 =$$

$$= \frac{1}{4} (f_0 - f_1 + f_2 - f_3)$$

$$c_1 =$$

$$=$$

$$c_3 =$$

$$= \frac{1}{4} (f_0 + i f_1 - f_2 - i f_3)$$

brauche Eulers form:

$$\sin(x) = \frac{1}{2i} (e^{ix} - e^{-ix})$$

$$\cos(x) = \frac{1}{2} (e^{ix} + e^{-ix})$$

$$\begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 6 \\ 3 \end{pmatrix} \rightarrow \text{einsetzen}$$

$$c_0 =$$

$$c_1 =$$

$$c_2 =$$

$$c_3 =$$

$$f(t) = c_0 + c_1 e^{it} + c_2 e^{2it} + c_3 e^{3it}$$

$$f(t) = \frac{1}{4} (11 - 4 \cos(t) - 3 \sin(t) + 5 \cos(2t) - 4 \cos(3t) + 3 \sin(3t)) + \frac{i}{4} (-4 \sin(t) + 3 \cos(t) + 5 \sin(2t) - 4 \sin(3t) - 3 \cos(3t))$$

Re()

Im()