Emergence of active nematics in chaining bacterial biofilms

Y. Ilker Yaman¹, Esin Demir², Roman Vetter ³ and Askin Kocabas^{1,4†}

¹Department of Physics, Koç University, Sarıyer, Istanbul, Turkey 34450

²Bio-Medical Sciences and Engineering Program, Koç University, Sarıyer, Istanbul, Turkey 34450

³Department of Biosystems Science and Engineering, ETH Zurich, 4058 Basel, Switzerland ⁴Koç University Surface Science and Technology Center, Koç University, Sarıyer, Istanbul, Turkey 34450

[†]Corresponding author: akocabas@ku.edu.tr

Abstract

Growing tissue and bacterial colonies are active matter systems where cell divisions and cellular motion generate active stress. Although they operate in the non-equilibrium regime, these biological systems can form large-scale ordered structures. How mechanical instabilities drive the dynamics of active matter systems and form ordered structures are not well understood. Here, we use chaining *Bacillus subtilis*, also known as a biofilm, to study the relation between mechanical instabilities and nematic ordering. We find that bacterial biofilms have intrinsic length scales above which a series of mechanical instabilities occur. Localized stress and friction drive buckling and edge instabilities which further create nematically aligned structures and topological defects. We also observe that topological defects control stress distribution and initiate the formation of sporulation sites by creating three-dimensional structures. In this study we propose an alternative active matter platform to study the essential roles of mechanics in growing biological tissue.

Introduction

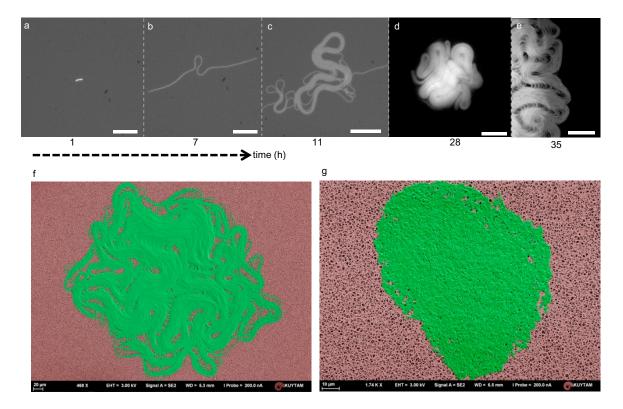
Biofilm formation is a collective response of bacteria¹⁻⁶. Depending on the availability of food and environmental conditions⁷, *B. subtilis* produce matrix proteins and initiate the formation of a biofilm². During biofilm development, motile bacteria differentiate into an aligned chain of cells. Growing chains further develop fibers and bundles which shape the overall biofilm morphology⁸⁻¹³. These distinct aligned structures promote sliding of a colony on a solid surface where the swimming behavior is not efficient¹⁴.

Aligned cellular structures are also observed in a variety of biological phenomena. During wound healing, migrating cells align and form fingering structures at the leading edge of the tissue¹⁵. Similarly, cultured cells¹⁶⁻¹⁸ and isolated bacteria colonies can form nematic alignment and modulate the cellular density and active stress¹⁹⁻²³.

Recent studies have shown that liquid crystal theory can provide a suitable framework to study

the dynamics of growing tissue as an active nematic system. Mainly, the dynamics of cellular alignment, topological defects, and edge instabilities have been explored¹⁶⁻²⁰. During growth mechanical instabilities also play essential roles by generating large structural folding. Growing aligned fibers and bundles can accumulate stress and buckle. The dynamics of active nematics and mechanical properties of growing material are intricately coupled. However, we do not know how the mechanical instabilities drive the dynamics of active nematics and form ordered structures.

Here, by investigating the formation of a bacterial biofilm starting from a single bacterium, we study the detailed mechanical instabilities driving the formation of a nematic active matter. We reveal the direct relation between local stress, localized buckling and edge instabilities. This system provides new mechanical insights to explore the complex dynamics of biological active nematics $(AN)^{24-28}$.



Results

Figure 1 Emergence of active nematics in a bacterial biofilm. Snapshots of a growing biofilm. a The bacterium initially elongates and forms a bacterial chain through proliferation (t = 2.5 h). Scale bar, 30 µm. b Due to local stress, the chain of attached bacteria buckles (t = 7 h). Scale bar, 30 µm. c Multilayered and circular structures appear at the region where the localized buckling takes place (t = 11 h). Scale bar, 30 µm. d The biofilm formation (t = 28 h). Scale bar, 150 µm. e Kink bands appear and separate different domains across the biofilm. Scale bar, 30 µm. Scanning electron microscopy images of f the biofilm formed by GFP labeled laboratory strain 168 (BAK47) and g the isolated bacterial colony formed by the non-chaining strain. All colonies were grown at $T = 21 \, {}^{\circ}C$.

Formation of chaining bacterial biofilms. We first used time-lapse fluorescence microscopy to observe the temporal evolution of a biofilm formation. Figure 1 shows the snapshots from the growth of a chaining *B. subtilis* biofilm, laboratory strain 168 (Fig. 1). This strain apparently forms a biofilm on a solid agar surface. Initially, divided cells give rise to a long and straight chain of attached bacteria. After several cell divisions, the first mechanical instability occurs (Supplementary Movie 1).

Interestingly, unlike Euler instability, this initial buckling is very localized. As the bacterial chain grows, the buckled region forms a crumpled structure (Fig. 1c). Some parts of this structure become multilayered and circular. Similarly, these multilayered structures continue to grow radially, and they split into two (Supplementary Figure 1). Moreover, sharp walls appear across the biofilm, and these bands are observed as dark lines separating different domains in fluorescence images (Fig. 1d, e). All the basic dynamics and shapes described above were observed repeatedly across the biofilm and generate perfectly aligned cellular structures (Fig. 1f). This aligned structure and its dynamics strongly resemble the nematic active matter systems, particularly microtubule-based AN^{27,28} (Supplementary Movie 2, 3, 4).

To clarify the structural differences between nematic biofilm and isolated bacterial colony, we grew a similar but non-chaining *B. subtilis* strain (BAK51, a derivative of 3610) under the same environmental conditions. This wild isolate failed to form chaining on an agar surface but can form a biofilm at a later stage stochastically (Supplementary Movie 5). In our bacterial strains, the flagella producing gene (*hag*) was also mutated to eliminate the swimming induced motion. Detailed scanning electron microscopy (SEM) images show tightly packed cells with fairly smooth colony edges (Fig. 1g, Supplementary Figure 2).

Clear nematic alignment of the biofilm required optimization of several parameters. First, we reduced the growth rate by decreasing the ambient temperature to eliminate the twisting and breakage of a bacterial chain (Supplementary Figure 3). Second, GFP (Green fluorescent protein) labeling is essential to observe finely aligned structures, but low power fluorescence excitation is also necessary to eliminate light toxicity during biofilm development.

Localized buckling. Localized buckling appears to be the first building block of the nematic biofilm (Fig. 2a, Supplementary Figure 4). To explore the physical mechanism underlying localization, we quantified the buckling condition. The localized buckling occurs just after reaching the critical chain length. As the chain continues to grow, extended arms follow the same localized buckling scenario (Fig. 2d, e).

The elasticity theory explaining the localization of the buckling is surprisingly complex. Both linear and nonlinear elastic properties of soft materials can contribute to the localization and formation of the post-buckling shape²⁹⁻³⁴. However, the theoretical framework for growth-induced localized buckling is not well-studied. We have noticed that railroad thermal buckling³⁵ and growing plant roots³⁶ show a similar spatial localization profile. Therefore, we used the notation and the framework developed for these systems and followed the slender-body approximation to simulate the dynamics of a growing bacterial chain. Low ambient temperature eliminates the twisting process, thus we exclude the twisting dynamics, and we modeled the bacterial chain as an incompressible flexible elastic rod. Since the system is at low Reynolds

number regime, we neglected the inertial forces and used the equations for mechanical equilibrium (see Supplementary Note 1 for the detailed derivations). First we compared the buckling profiles of the growing rod under viscous drag force and uniform friction. We observed that the viscous drag force alone generates a global buckling profile. Similar global buckling shapes were also observed in growing liquid crystals³⁷. However, uniform friction force provides linear compressive tension profile which can localize the buckling. Further, we implemented a more realistic bacterial adhesive forces model, recently developed by Duvernoy et al.³⁸ to test the localization. In this model interactions are based on local adhesion between bacteria and agar surface. Adhesive bonds are formed at a fixed rate and break when they experience the force larger than a threshold force. We also found that this model provides more localized tension profiles (Supplementary Figure 5). Similarly, the tension locally exceeds the critical buckling limits when the total length reaches the threshold. Our numeric simulations show that both uniform friction and adhesion models can create localized buckling. This buckling condition sets a length scale for a bacterial chain. The detailed comparison of the tension profiles are given in the supplementary section.

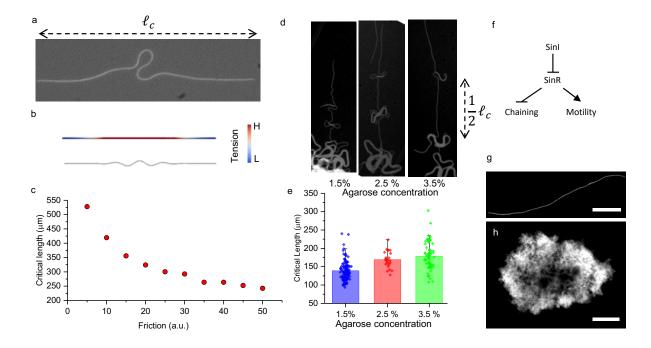


Figure 2 Localized buckling of a bacterial chain. a A snapshot of a bacterial chain with a length just above the critical buckling length. The buckled region is highly localized due to b localization of stress generated by the uniform friction force. The stress accumulates from the tip to the center of the chain due to outward axial velocity. The uniform friction force creates an almost linear stress distribution along the chain. c Plot of critical buckling length against friction, simulation results. Inlet shows a snapshot of the simulation just after the buckling and the color code shows the tension at pre-buckling stage. d Successive localized buckling instabilities on 1.5 %, 2.5 %, and 3.5 %, respectively. After the first buckling, the subsequent buckling occurs at the middle of the straight part of the chain, which implies that the stress is symmetric around the center, and the connection of the former buckling region with the straight part is effectively a free end. Therefore, the separation between buckled regions is equal to half of the critical buckling length. e Experimental results of the critical buckling length for various

agarose concentrations. The data is collected from more than 100 chains. Error bars are defined as s.d. **f** Schematic of a simplified regulatory network that controls the biofilm formation. The protein sinI regulates the chaining state through double-negative feedback. **g**, **h** Bacterial chain grown in liquid LB. **g** The chaining formation is initiated by IPTG induction. **h** In the later stages, the colony forms a biofilm via supercoiling. Scale bar, 50 μ m (**g**) and 200 μ m (**h**).

Finite Element Simulation of growing biofilms. To further quantify the buckling conditions, we performed FEM (Finite Element Method) simulations based on recently developed algorithms used to study growing elastic structures³⁹⁻⁴¹. In these simulations we used uniform friction between a growing rod and a surface. Using realistic bacterial parameters, we found that an increase in friction force reduces the critical length (Fig. 2b, c). To experimentally verify this effect, we tuned the agarose concentration which serves as a flat surface and imaged the periodically buckled regions of a single bacterial chain. Our experiments revealed that the critical length changes with the agarose concentration (Fig. 2d, e). Typically, the bacterial chain becomes unstable above $138\pm26\mu m$. Interestingly, high agarose concentration reduces the friction force and increases the critical length. The exact mechanism behind the friction⁴² is not clear to us; we speculate that the soft agar surface allows more local deformations and changes the local binding dynamics which may increases the friction force. We also observed that the growth rate of the biofilm does not significantly change the critical length. This result suggests that dynamics is overdamped by the friction (Supplementary Figure 6).

Further, we tested the local buckling in a liquid environment which eliminates the friction force. In its wild-type form, *B. subtilis* suppress biofilm formation in liquid LB (Luria-Bertani broth) culture. Detailed molecular genetics studies have identified that protein sinI initiates and maintains the chaining state through double-negative feedback^{1,3,4} (Fig. 2f). To trigger biofilm formation in liquid, protein *sinI* should be overexpressed. To overcome this limitation, we used a genetically modified strain to drive *sinI* using IPTG (Isopropyl β-D-1-thiogalactopyranoside) based induction (the background strains TMN1152 were received from R. Losick Lab). When we grew the biofilm in liquid culture with IPTG, local buckling disappeared, but the supercoiling process dominated the formation of the biofilm (Fig. 2g, Supplementary Movie 6, 7). We further clarified the structure of supercoiled bundles using fluorescence time-lapse microscopy and SEM imaging (Supplementary Figure 7). Experimentally we observed variations in the shapes of early buckled bacterial chains (Supplementary Figure 4). This variation is most likely originating from the surface heterogeneity. However, localized buckling feature is conserved in all bacterial chains. Altogether, we showed that friction force between the agar surface and the bacterial chain controls the mechanical instability. Localization of stress further generates spatially localized buckling and defines the critical length scale for a biofilm.

Edge instabilities. As a second step, we focused on the edge instabilities of a growing biofilm. The growing multilayered circles are the most distinct geometric features observed around the leading edge (Fig. 3a). At first glance, the dynamics of these structures resemble the instabilities of smectic-A liquid crystal filaments^{37,43}. These circles are connected to the film with a tail, and they grow like droplets. As they grow outward, instability occurs, and the droplets split into two. As gleaned from previous studies, we tested whether these structures have a characteristic critical radius which triggers new mechanical instabilities. We performed FEM simulations to observe the splitting dynamics. First, we simulated the growing multilayered circular structure with a tail

(Fig. 3b, Supplementary Movie 8). We found that these structures indeed have a critical radius. Above this radius, circular structures are unstable and split into smaller but stably growing ones. As we observed in previous experiments, the straight tail also locally buckles in the direction perpendicular to the growing axis after reaching the critical length. Our simulation verified that edge instability occurs when the circumference of the circular structure exceeds the linear critical length $2\pi R_c = \ell_c$ (Fig. 3c, d). We confirmed this relationship experimentally. Similarly, both a critical radius and a critical length are controlled by friction.

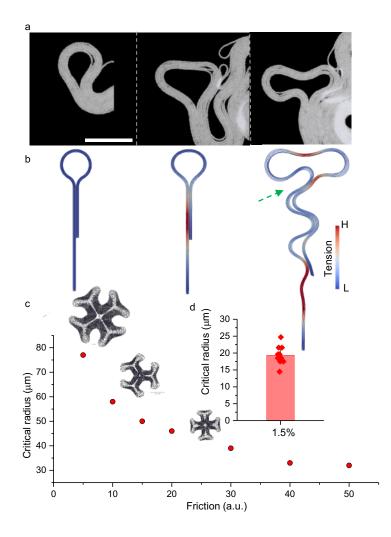


Figure 3 Edge instabilities of a growing biofilm. a Snapshots of growing multilayered circles. The radius reaches the critical radius and splits into two. Scale bar, 30 µm. b Snapshots from the simulation of a droplet-like structure with a long tail. Color code shows the stress level. While the droplet splits into two circles, the long tail locally buckles since its length is above the critical buckling length. Green arrow shows the secondary buckling region which asymmetrically folds the circular structure on to the colony edge. c Multilayered growing circles are simulated under various friction forces. The plot of critical radius against friction, simulation results. Units are arbitrary. All snapshots were taken as the secondary edge instability occurred. d Experimental data of the critical radius. The colonies were grown on 1.5 % agarose concentration. Error bar is defined as s.d.

We also observed that, just after the splitting, an additional buckling might occur around the junction point (connection between the droplet and the tail) where the chain has the highest curvature (green arrow in Fig. 3b). This buckling further makes the divided droplet fall back on the biofilm edge asymmetrically (Supplementary Figure 8). We then extended our simulations to observe large-scale biofilm growth starting from many concentric circular rods or multilayered structures (Supplementary Movie 9, 10). In our simulations initial filament configurations can also affect the final colony shape. U shaped multi-layered structure gives more realistic colony morphology (Supplementary Figure 9, 10). As expected, friction also shapes the overall biofilm morphology by defining the maximum radius of the curvature around the leading edges (Fig. 3d). Altogether our results show that a growing biofilm has a critical radius which controls the dynamics of edge instabilities. It should be noted that the instabilities of a biofilm structure is mainly defined by the competition between elastic deformation of a growing rod and the rod-surface interactions. Friction or adhesion forces are responsible for the rod-surface interactions and control the instabilities. Addition to the friction force, the elastic modulus of the filament can directly change the buckling conditions (Supplementary Figure 11).

Dynamics of topological defects. One of the characteristics of active nematics is the formation of topological defects^{16-18,27,28,44}. To better understand the active matter nature of a biofilm, we further focused on how mechanical instabilities generate topological defects. In microtubulebased active matter systems, topological defects (+1/2 or -1/2) (Fig. 4a) are spontaneously created and annihilated. The exact mechanism behind the creation of these defects remains unknown⁴⁵. Recent studies elegantly demonstrate that the confinement controls defects formation⁴⁵⁻⁴⁷. In contrast, our biofilm system does not require any physical confinement which enables the edge to move freely and allows observation of the evolution of the defect formation. Analyzing the development progress, we found two main defect forming mechanisms; the large-scale biofilm folding and edge instabilities.

Using time-lapse microscopy, we recorded the first defect generation process. As it grows, the entire biofilm reaches the critical length scale and triggers large structural folding (Fig. 4b, c). This folding forms $\pm 1/2$ defects. Fig. 4 shows the temporal evolution of this defect formation. As observed, the biofilm sequentially folds in orthogonal directions and generates several motile $\pm 1/2$ defects (Supplementary Figure 12). Clearly, in this stage the total number of defects increases. As the size of a biofilm increases, the critical length drops below the biofilm size, and this type of folding appears locally (Supplementary Movie 2, 3). In bulk active matter systems, defects are generated in pairs. However, active matter systems with boundaries can generate $\pm 1/2$ defect penetrating into the system from the edge. Figure 4 j, k shows the simulation results representing this unconventional defect forming mechanism.

We also found that the edge instabilities can be considered as a second type of defect forming mechanism which is often observed in bulk active matter systems. Growing droplet geometries around the edge simply behave like +1/2 topological defects (Fig. 4d). These structures are very motile, because the unbalanced force generated by the growing side chains can push the defect forward. In contrast to the structural folding described above, this growing droplet splits into two and generates paired +1/2 defects, and it leaves one -1/2 defect around the junction point (Fig. 4e, j). This mechanism keeps the total topological charge constant. At later stages foldings and splittings become strongly coupled. Thus, the dynamics of defect formation become very

chaotic.

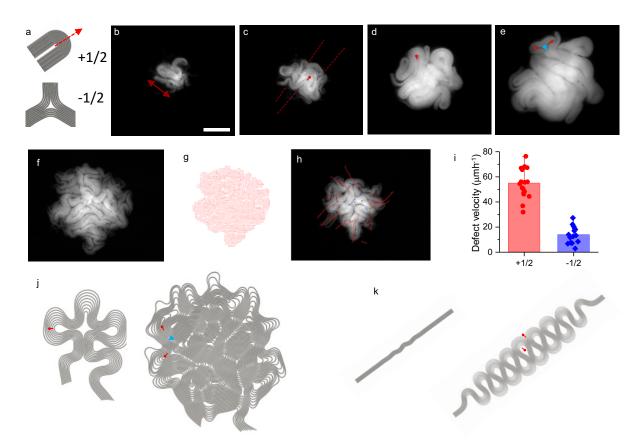


Figure 4 **Dynamics of topological defects.** a Comet-like motile (+1/2) and trefoil-like (-1/2) topological defects. **b**, **c**, **d**, **e** Snapshots of a growing biofilm. **b** Biofilm elongates and reaches the critical buckling length. Scale bar 100 µm. **c** As a result, biofilm shows a structural folding and creates (+1/2) topological defects. **d**, **e** (+1/2) topological defects at the edge move outward, split into two (+1/2) defects and create a (-1/2) defect at the junction. **f** Snapshot of a growing biofilm. **g** The director field of the biofilm (**f**). **h** Trajectories of both (+1/2) and (-1/2) defects. Red lines indicate the trajectories of (+1/2) defects which are motile, whereas blue lines represent the trajectories of (-1/2) defects. Error bars are defined as s.d. **j**, **k**, Simulation results of a growing multilayered structures. **j** (+1/2) defect splits and forms paired (+1/2) red dots) and (-1/2) blue dot) defects. **k** Large colony folding forms only (+1/2) defects (red dots).

Our simulations verified the dynamics of defect formation around the edge. We observed that above the critical radius both outward and inward propagating bucklings appear. Accumulated localized stress gradually slow down the speed of the central region and then starts migrating inward. These inward propagating chains might collide with the junction point and then become a stationary -1/2 defect by leaving two motile paired +1/2 (Supplementary Movie 9, 10).

Notably, some of the propagating defects leave king bands as a clear trace (Fig. 4f). These bands originate from the differences in the radius of multi-layered structures which eventually define

the total growth rate of the circumference.

To further examine defect formations experimentally, we measured the speed distributions of defects within a biofilm (Fig. 4i). We found that +1/2 defects are more motile around the edge and -1/2 defects are stationary. We also noticed that as the biofilm develops the central region becomes stationary. We measured the GFP signal around the center and noticed that the growth of the biofilm does not slow down (Supplementary Figure 13). The most parsimonious hypothesis based on these observations is that stress accumulates around the center and slows down the dynamics.

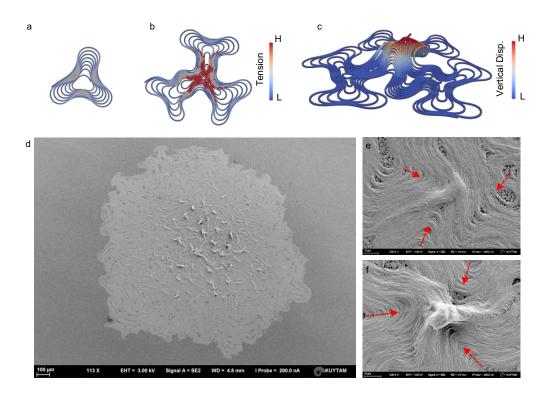


Figure 5 Accumulation of stress and vertical lift-off. a, b, c Simulation results of a growing multilayered circular colony. a After reaching the critical radius, the colony folds and creates topological defects. b Inward propagating defects collide and create a (-1/2) defect. The stress is accumulated at the collision point, namely (-1/2) topological defect. c The accumulated stress results in vertical lifting around the (-1/2) topological defect. d, e, f SEM images of a biofilm in late stage. Red arrows indicate the propagation directions of the defects. d Vertically lifted domains are in the vicinity of the center where the stress accumulates. e Motile (+1/2) defects collide and form a stationary (-1/2) defect. f Accumulation of stress causes vertical lift-off.

Defect mediated stress and formation of sporulation sites. Topological defects could also change the physiology of the biological tissues^{18,48-50}. It was shown that defect-induced stress triggers mechanotransduction and alters the genes expressions¹⁶. Stress also modulates the cellular density of cultured cells. Topological defects and active stress could also play a biophysical role during the development of a biofilm. With this motivation, we further performed

stress analysis of topological defects. Our simulations revealed that the stress accumulates as stationary -1/2 defect occurs (Fig. 5 a, b). Around these defects, the unbalanced force generated by the growing chain can be balanced by counter propagating ones. Further, colliding bent chains significantly increase total stress. When we performed our simulation in the three-dimensional domain (so far we performed all simulation in a 2D confined environment), we observed vertical lifting of the elastic rods around the vicinity of -1/2 defect (Fig. 5c, Supplementary Movie 11).

We asked whether we could experimentally observe the effects of stress accumulation in a biofilm. To do so, we analyzed the 3D surface topology after getting a stable biofilm (35 h after seeding). SEM images revealed vertical structures around the -1/2 defects sites (Fig. 5d, e, f). A close investigation clarified that these structures are actually the vertically lifted parts of the defects. These structures are more visible around the center of the biofilm. We grew the non-chaining bacteria in the same conditions and we did not observe any of these vertical structures (Supplementary Figure 14). Isolated bacterial colonies can form multilayered structures but do not form a verticle structure (Supplementary Figure 15). The results are remarkably consistent with our FEM simulations. These structures have already been identified as aerosol or fruiting bodies of the biofilm which eventually produce bacterial spores². We do not exclude other structural instabilities or the contribution of the twisting process. Our results support the idea that topological defects are one of the possible origins of these vertical ordered geometries. Finally, we tested the instabilities of growing *E. coli* biofilm structure⁵¹. A colony of isolated *E. Coli* provide a smooth leading edge. However, biofilm-forming *E. coli* also share similar buckling and edge instabilities (Supplementary Figure 16).

Discussion

The theory of active nematics provides a robust framework to explain the coordinated motion of cells and the emergence of large-scale order in biological systems. Our study throws light upon mechanical aspects of biological active matter systems: First, mechanical instabilities can be simply characterized by a critical length scale. Different types of length scales have previously been defined for various AN systems^{24,26}. These quantities mainly describe the activity of the system. In contrast, our length scale reflects the elastic properties of the biofilm which is mainly defined by the competition between elastic deformation of chaining bacteria and the bacteriaagar interactions. Second, the leading edge of the biofilm is not stable. Edge instabilities^{15,44,52-54} have received significant attention due to fingering formation during wound healing¹⁵. Our results revealed the importance of cellular alignment and localized stress driving instabilities. Finally, we have shown the formation of the defects and their effect on the stress distribution across the biofilm. In growing tissue or bacterial colonies, mechanical stress can easily result in physiological stress. Recent studies have linked the physical forces with the cellular response¹⁶, and our system could further reveal the importance of stress management across growing tissue⁵⁵. Another benefit of using *B. subtilis* is the availability of sophisticated genetic toolbox⁵⁶. Genetic manipulations and control could reveal unexplored dynamics of active matter systems. We believe, our biofilm platform offers new opportunities to study active nematics in living systems.

Methods

Sample preparation and growth conditions. Bacterial cultures (BAK47 and BAK51) were grown in Luria-Bertani (LB) broth at 37 °C on a shaker. An overnight culture was diluted 100x and grown 8 h. The culture was diluted 10000x, and 50 μ l of culture was seeded on an LB agarose plate. These isolated bacteria on plates were grown at 21 °C for 12 h then imaged. The cover glass was not used during imaging. IPTG (isopropyl β -D-1-thiogalactopyranoside) inducible bacteria (BAK50) were grown in LB broth at 37 °C without IPTG induction to ensure that chaining does not occur. An overnight culture was diluted 10000x and supplemented with 100 μ M IPTG. A droplet of IPTG inducible bacterial suspension is placed between two glass slides with 100 μ m separation, then imaged at 21 °C. Strains used in experiments are described in Table 1.

Strain	Parent	Operation	Genotype
BAK47	168	Transformed with plasmid ECE321 from Bacillus Genetic Stock Center	amyE::Pveg-sfGFP (Spc)
BAK50	TMN1152	Transformed with plasmid ECE321 from Bacillus Genetic Stock Center	amyE::Pveg-sfGFP (Spc) ywrK::Pspank-sinI (Spc)
BAK51	TMN1138	Transformed with plasmid ECE321 from Bacillus Genetic Stock Center	<i>amyE::</i> Pveg-sfGFP (Spc)
			sacA::Phag-mKate2L (Kan)
			hagA233V (Phleo)
BAK 55	DH5alpha	Transformed with plasmid 107743 from Addgene	pBad-ag43, pDawn-sfGFP

Table 1 Strain list used in this study.

Escherichia coli biofilm formation. *E. coli* bacterial cultures (BAK55) were grown in Luria-Bertani (LB) broth at 37 °C on a shaker. An overnight culture was diluted 100x and grown 8 h. The culture was diluted 10000x, and 50 μ l of culture was seeded on YESCA plates and were grown at 37 °C. On regular LB plates and at room temperature *E. coli* do not form a biofilm.

Microscopy imaging. Fluorescence time-lapse imaging was performed using a Nikon SMZ18 stereo microscope and images were obtained using a Thor Labs DCC1545M CMOS camera. Time intervals between successive images are 15 minutes. To obtain the best image quality, the light exposure is controlled adaptively for different colony sizes by a custom-written program in LabVIEW. A typical colony growth experiment was run for 1 day.

SEM imaging. Before seeding the bacteria on LB agar surface, sterile filter paper with pore size 0.2 μ m is placed on the surface. After seeding the bacteria on the filter paper, bacteria were grown on the paper for 24 h at 21 °C. Then the filter paper was peeled off from the surface, and the colonies were fixed using paraformaldehyde and left to drying. Fixed colonies were imaged using Zeiss Ultra Plus Field Emission Electron Microscope.

Image analysis and detection of topological defects. Images were smoothed using Bandpass filter in ImageJ, and Coherence-Enhanced Diffusion Filter was applied to images in MATLAB. The ImageJ plugin OrientationJ was used to find the nematic director field of the colony. We followed the defect detection algorithm²⁷ using a custom-written MATLAB code.

Computer simulations. For the computer simulations involving large growth, we employed a dynamic finite element program³⁹⁻⁴¹. The filament was modeled as an isotropic, linearly elastic continuum with three-dimensional beam theory using cubic Hermite shape functions and a corotational quaternion formulation for geometric nonlinearity. The filament was assumed to have a circular cross-section with constant uniform radius $r = 0.7 \mu m$, a Young's modulus of E = 5300Pa (corresponding to a bending stiffness of $E(\pi/4)r^4 = 10^{-21}$ Nm²), a Poisson ratio of 1/3 and a mass density of 1gcm⁻³. The elastic energy of the filament consisted of the sum of bending, torsion and axial compression energies. Hertzian repelling forces were exchanged between contacting filament elements in normal direction, whereas the tangential contact forces were realized with a Coulomb slip-stick friction model. Newton's equations of motion were integrated in time with a second-order predictor-corrector scheme. For numerical robustness and to keep the filament near static equilibrium during growth, subcritical damping forces were added. The initial configuration was assumed to be stress-free, and the filament was grown exponentially in length over time, according to $\ell(t) = \ell_0 e^{\sigma t}$ where σ is the exponential growth rate. This was realized by continuously increasing the equilibrium length of each rod element. The substrate was modeled as an ideal elastic horizontal plane onto which the filament was placed, and a gravitational force was applied perpendicular to the plane.

Data Availability

All data supporting findings in this study are available from corresponding authors on request.

Code Availability

All custom codes used in this study are available from corresponding authors on request.

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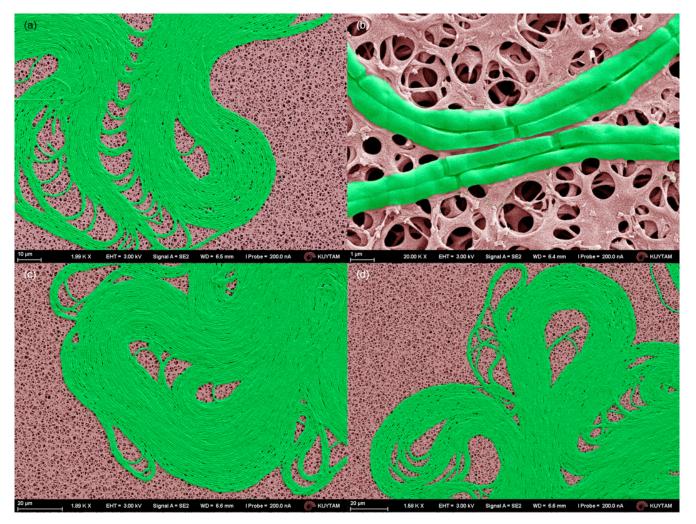
Author contributions

Y.I.Y. and A.K. designed and performed experiments, analyzed data and developed the imaging systems. Y.I.Y., E.D., and A.K. performed the molecular biology experiments. R.V. designed and developed the FEM simulation toolbox and optimized the codes with realistic bacterial parameters. Y.I.Y. performed the simulations. Y.I.Y. and A.K. prepared the draft, and all authors contributed to the final writing of the manuscript.

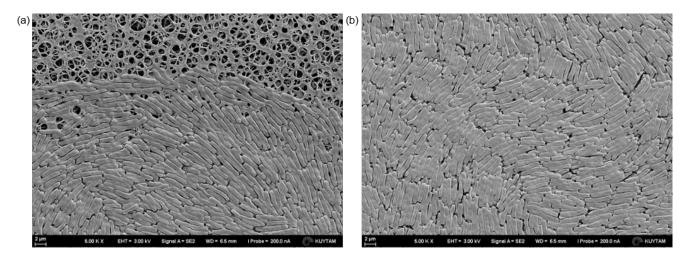
Competing interests

Authors declare no competing interests.

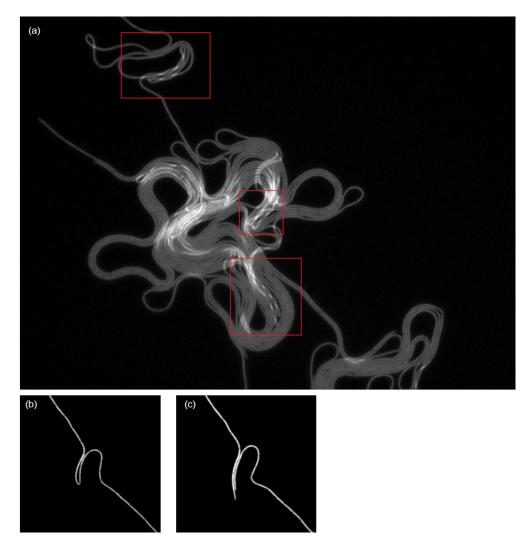
Supplementary Figures



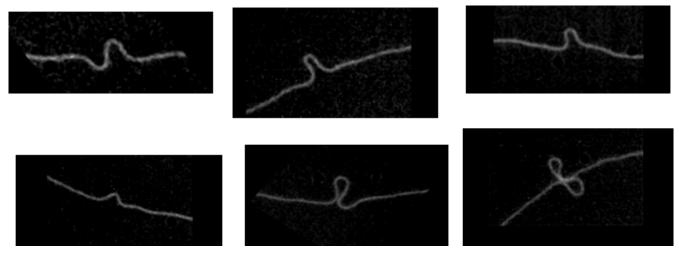
Supplementary Figure 1: **SEM images of bacterial biofilm** (BAK47). (a), (b), (c), (d) SEM images of chaining bacteria on a filter paper. Circular multilayered structures, aligned chains, and kink bands appear during biofilm growth.



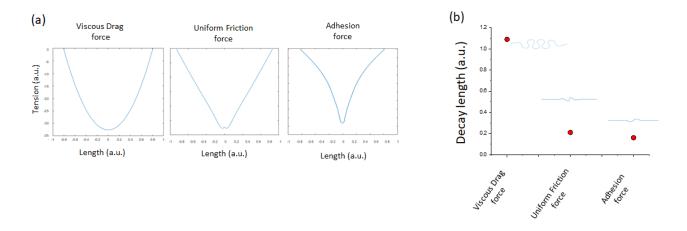
Supplementary Figure 2: **SEM images of the non-chaining bacterial strain** (*BAK51*). (a) Tangentially oriented cells form a smooth boundary layer. (b) Cells are nematically oriented and tightly packed.



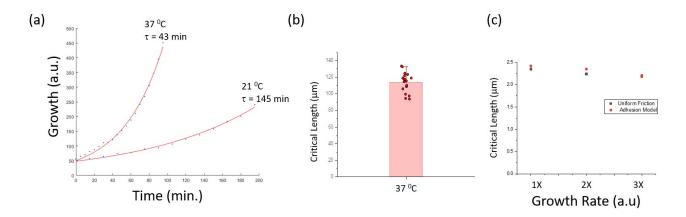
Supplementary Figure 3: Twisting and breakage of a bacterial chain. Images of a growing biofilm at $37^{\circ}C$. (a) Supercoiled structures are indicated with red boxes. (b), (c) Snapshots are showing the breakage of a buckled chain during growth.



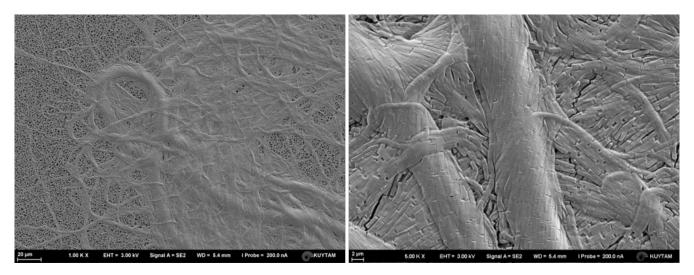
Supplementary Figure 4 Early buckling shapes of the growing bacterial chains. Surface heterogeneity creates different buckling shapes. However, all of them share the same localized profile.



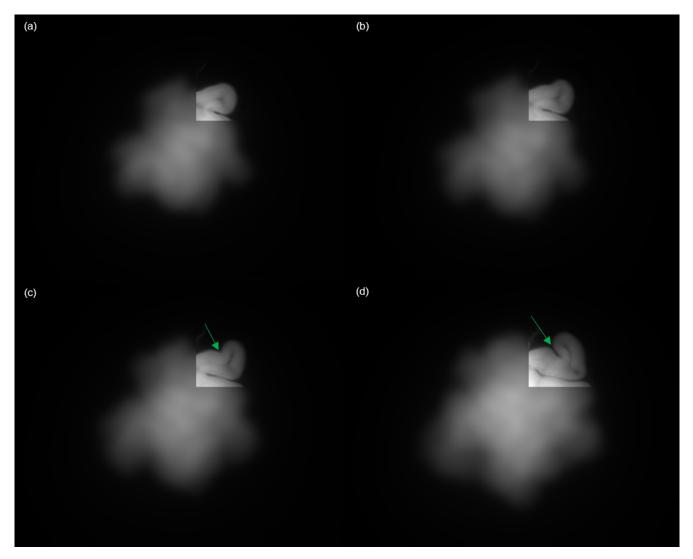
Supplementary Figure 5: **Global versus local buckling.** Viscous drag force generates global buckling. (a) Simulation of tension and buckling profiles of growing rods under different forces; viscous drag, uniform friction and adhesion-based model. (b) Decay lengths of the buckling profiles under different friction force models. Both, uniform friction and adhesion model can localize the buckling around the center.



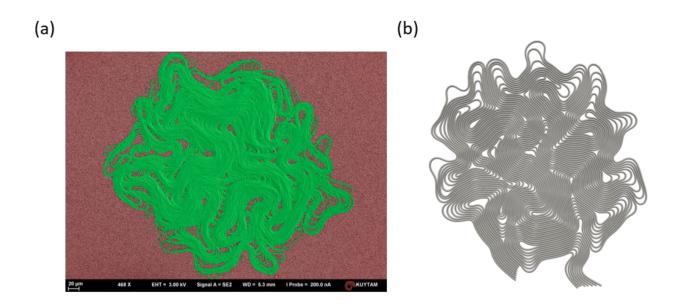
Supplementary Figure 6: **Temperature dependence of biofilm formation.** (a) Growth curves of the biofilms at different ambient temperatures. (b) Distribution of the critical length measured at $37^{\circ}C$. We observed a small decrease in the critical length. Error bar is defined as s.d. (c) Numerical simulation of critical length as a function of growth rate for both uniform friction and adhesion models.



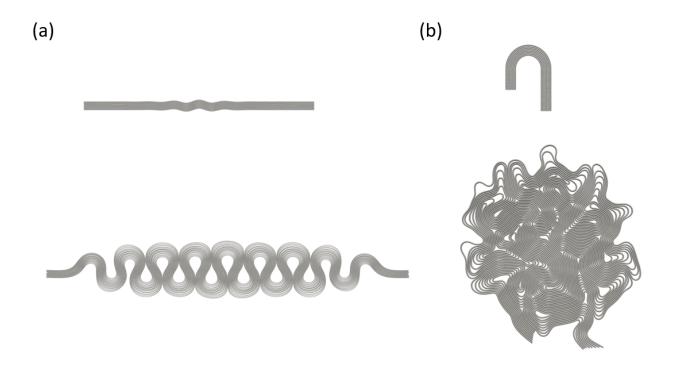
Supplementary Figure 7: SEM images of supercoiled bundles. Strain BAK50 was grown in liquid LB culture.



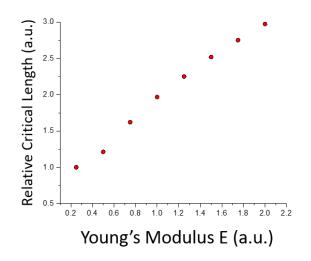
Supplementary Figure 8: Asymmetric splitting of a droplet-shaped structure. (a), (b), (c), (d) Snapshots from the biofilm on 1.5% agar surface. Green arrows show the additional buckling creating asymmetric splitting of the defect.



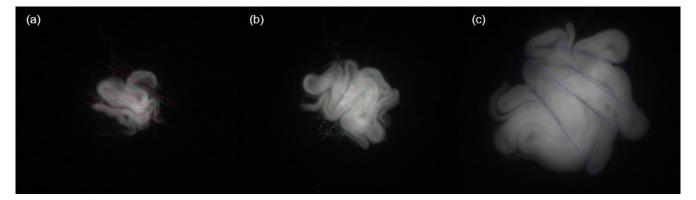
Supplementary Figure 9: Comparison of a real and simulated chaining bacterial biofilms. (a) SEM image of a biofilm. (b) Snapshot from the simulation.



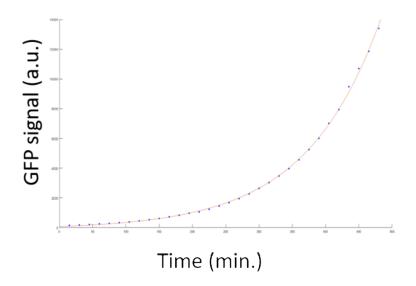
Supplementary Figure 10: Simulation of growing colonies starting from different initial shapes. (a) Linear and (b) U-shaped multilayered structures used as initial shapes. U-shaped initial configurations give rise to circular colony observed in the experiments.



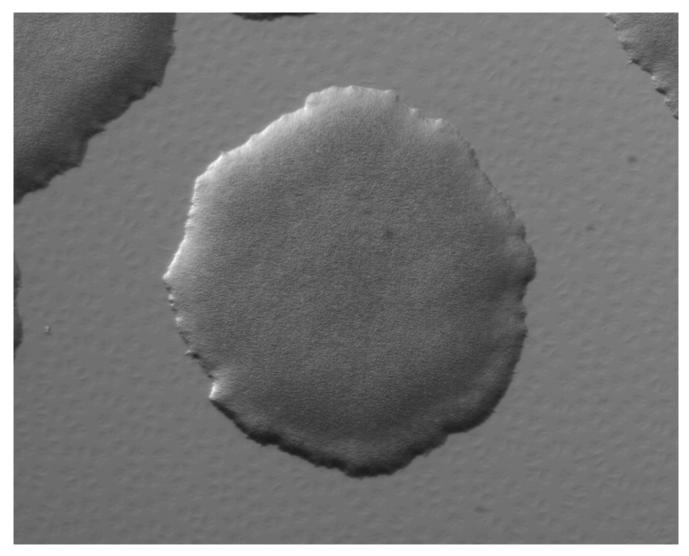
Supplementary Figure 11: Simulation of relative critical length as a function of Young's modulus of a growing rod. The critical length increases with the higher Young's Modulus values.



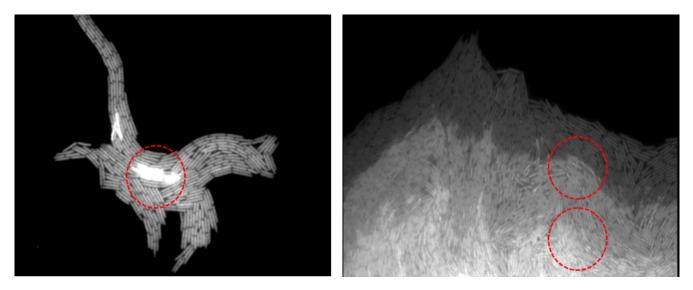
Supplementary Figure 12: Large-scale structural folding of a biofilm. Defect-creating large-scale structural buckling mechanism is observed for the biofilms at the size above the critical length. (a), (b), (c) show successive folds in orthogonal directions. Colored lines show the propagation directions of the topological defects.



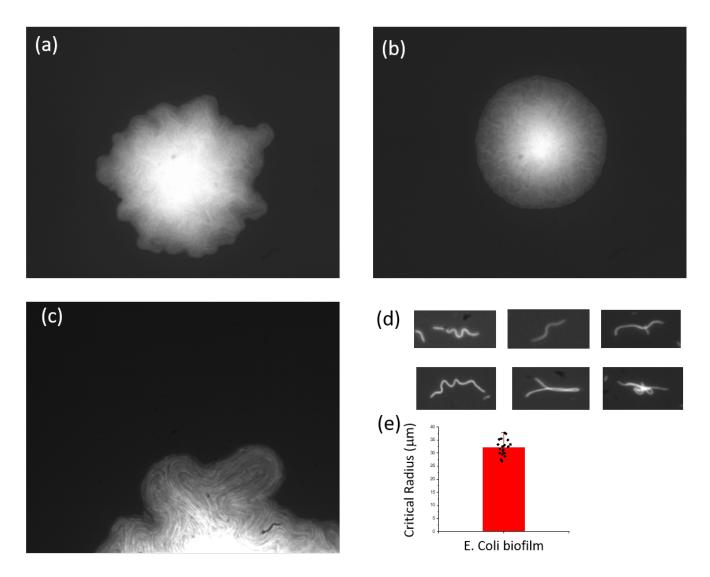
Supplementary Figure 13: Growth curve of the biofilm. GFP signal as a function of time shows normal growth profile. Time constant was measured to be t = 150 min at room temperature.



Supplementary Figure 14: The isolated bacterial colony of non-chaining *B. subtilis* strain (*BAK51*). Bright-field image of the colony grown on 1.5% agar surface. Vertical fruiting bodies not observed.



Supplementary Figure 15 **Double and multilayer formation in isolated bacterial colonies.** Red circles indicate the regions. Instead of forming vertical structures, these layered regions gradually cover the colony. The transition can be observed around the edge.



Supplementary Figure 16 Edge instabilities and local buckling of *E. coli* biofilm. a) Biofilm forming *E. coli* on YESCA plates forms strong edge instabilities. b) *E. coli*, growing on regular agarose (LB) plate form smooth colony edge. c) Similarly, above the critical radius circular growing patterns split. d) Sample images of early buckling shapes of chaining *E. coli*. e) Distribution of critical radius of the *E. coli* biofilm. Error bar is defined as s.d.

Supplementary Table 1: The parameters used in the simulations based on adhesion model

$\nu = 1$ Drag coefficient		
EI = 1	EI = 1 Bending modulus	
$\ell = 1$	Initial length of the rod	
$\sigma = 100$	Exponential growth rate	
$k_{on} = 5e4$	Adhesin attachment rate	
$k_{off} = 2$	Adhesin detach rate	
$L_0 = 0.05$	See eqn. (13)	
A = 60	See eqn. (13)	
$F_{link}=60$	See eqn. (14)	
n = 50	Max. number of adhesins per node	

Supplementary Note 1: Numerical simulations of a growing rod

The equation of motion describing the dynamics of an inextensible growing rod under external forces in a viscous environment is:

$$\nu \mathbf{x}_t = -EI\mathbf{x}_{ssss} + \mathbf{f}_{ext} + \partial_s(T\mathbf{x}_s) \tag{1}$$

Here, ν is the local drag coefficient of the fluid, EI is the bending modulus of the rod and T is the tension on the rod. Subscripts s and t denotes the differentiation with respect to arclength parameter and time respectively. The growth condition for the exponentially growing rod is:

$$\mathbf{x}_s \mathbf{x}_{st} = \sigma \tag{2}$$

Where σ is the exponential growth rate of the rod. Differentiating eqn. (1) with respect to arclength gives:

$$\nu \mathbf{x}_{st} = -EI\mathbf{x}_{sssss} + \partial_s \mathbf{f}_{ext} + \partial_{ss}T\mathbf{x}_s + T\mathbf{x}_{sss} + 2\partial_s T\mathbf{x}_{ss}$$
(3)

By multiplying both sides with the unit tangential vector we get:

$$\nu \mathbf{x}_s \mathbf{x}_{st} = -EI \mathbf{x}_s \mathbf{x}_{sssss} + \mathbf{x}_s \partial_s \mathbf{f}_{ext} + \partial_{ss} T \mathbf{x}_s \mathbf{x}_s + T \mathbf{x}_s \mathbf{x}_{sss} + 2\partial_s T \mathbf{x}_s \mathbf{x}_{ss}$$
(4)

By using the following identities and eqn. (2), we have:

$$\mathbf{x}_{s}\mathbf{x}_{s} = 1; \ \mathbf{x}_{s}\mathbf{x}_{ss} = 0; \ -\mathbf{x}_{s}\mathbf{x}_{sssss} = 4\mathbf{x}_{ss}\mathbf{x}_{ssss} + 3 |\mathbf{x}_{sss}|^{2}; \ \mathbf{x}_{s}\mathbf{x}_{ssss} = -|\mathbf{x}_{ss}|^{2}$$

$$\left(\partial_{ss} - |\mathbf{x}_{ss}|^{2}\right)T = 4EI\mathbf{x}_{ss}\mathbf{x}_{ssss} + 3EI |\mathbf{x}_{sss}|^{2} - \mathbf{x}_{s}\partial_{s}\mathbf{f}_{ext} + \nu\sigma$$
(5)

Numerical solution of eqn. (1) and eqn. (5) leads to the time evolution of a growing rod under external forces in a viscous fluid. In our case, we solved this equation for viscosity dominated, uniform friction dominated, and adhesion dominated system. For the viscous dominated system, the external force is zero. For the other two cases, we replaced \mathbf{f}_{ext} with uniform friction force or adhesion.

a. Viscous Drag Force Dominated System

First, we assume that viscous forces are dominating the filament dynamics and we analyzed the buckling shape of a growing rod. Therefore, we neglected all other external forces. Then the eqn. (5) becomes:

$$\left(\partial_{ss} - \left|\mathbf{x}_{ss}\right|^{2}\right)T = 4EI\mathbf{x}_{ss}\mathbf{x}_{ssss} + 3EI\left|\mathbf{x}_{sss}\right|^{2} + \nu\sigma \tag{6}$$

For a straight rod, $\mathbf{x}_{ss} = \mathbf{x}_{sss} = \mathbf{x}_{sss} = 0$ for any point. Therefore, equation (6) reduces to:

$$\partial_{ss}T = \nu\sigma \tag{7}$$

The solution of this equation with free end boundary conditions is a parabola:

$$T = -\nu\sigma \left(\frac{\ell - x}{2}\right)^2 \tag{8}$$

Here x is the position of a point on the straight rod and ℓ is the total length of the rod. The simulation of this condition are given in Supplementary Figure 1.

b. Uniform Friction Force Dominated System

To find the tension profile of this system, we neglected the viscous forces and assuming that the center of the rod is positioned at x = 0, we can write the external forces as:

$$\mathbf{f}_{\mathbf{ext}} = -f sgn\left(x\right) \mathbf{x}_s \tag{9}$$

Where f is the friction per unit length. By substituting \mathbf{f}_{ext} into eqn. (5), we get:

$$\left(\partial_{ss} - \left|\mathbf{x}_{ss}\right|^{2}\right)T = 4EI\mathbf{x}_{ss}\mathbf{x}_{ssss} + 3EI\left|\mathbf{x}_{sss}\right|^{2} - \mathbf{x}_{s}\partial_{s}\mathbf{f}_{ext} + \nu\sigma$$
(10)

We neglect the viscous term and by assuming the rod is straight and we get:

$$\partial_{ss}T = \partial_s f sgn\left(x\right) \tag{11}$$

The solution of this equation with free end boundary conditions provides a linear tension profile:

$$T = f(|x| - \ell/2)$$
(12)

c. Adhesion model

To implement the adhesion force, we used a recently developed model in which adhesive proteins dynamically attach and detach to the agar surface and the force is obtained by using the worm-likechain model¹. In our model, adhesins can be uniformly distributed along a single bacterium. These adhesins are created at a constant rate (k_{on}) throughout the chain until reaching the maximum number of adhesins per length (n), and detach above a critical force (F_{link}) . The force on a single adhesin is given by the following equation:

$$F_{\rm adh} = -A\left(\frac{L}{L_0} + \frac{1}{4}\left(1 - \frac{L}{L_0}\right)^{-2} - \frac{1}{4}\right)$$
(13)

L is the link extension and L_0 is a constant.

The detach rate of an adhesin depends on the force exerted on it. The detach rate is given by the following equation:

$$r(F_{\rm adh}) = k_{\rm off} \times \begin{cases} 1 + \operatorname{arctanh}\left(\frac{F_{\rm adh}}{F_{\rm link}}\right), \text{if } F_{\rm adh} \leq F_{\rm link} \\ \\ \infty, \text{ otherwise} \end{cases}$$
(14)

The parameters used in the simulations are listed in Supplementary Table 1.

Numeric solution of tension and buckling profiles of growing rods are given in Supplementary Figure 5. Viscous drag force provides global buckling profile. However, uniform friction and adhesive force model can provide localized tension and also trigger the localization of the buckling profiles. Supplementary Figure 5 shows the comparison of tension profiles and decay lengths of the buckling regions under different forces.

Supplementary References

1. Duvernoy, M.-C. et al. Asymmetric adhesion of rod-shaped bacteria controls microcolony morphogenesis. *Nat Commun* **9**, 1120, doi:10.1038/s41467-018-03446-y (2018).